

#### PICTERRA PLATFORM







WMS/WMTS/TMS

**DATA SOURCES** 

GENERATE
CUSTOMIZED
GEO-SPATIAL
INFORMATION

TRANSFER LEARNING



PLATFORM

**ACTIVE LEARNING** 

DETECTIONS & INSIGHTS



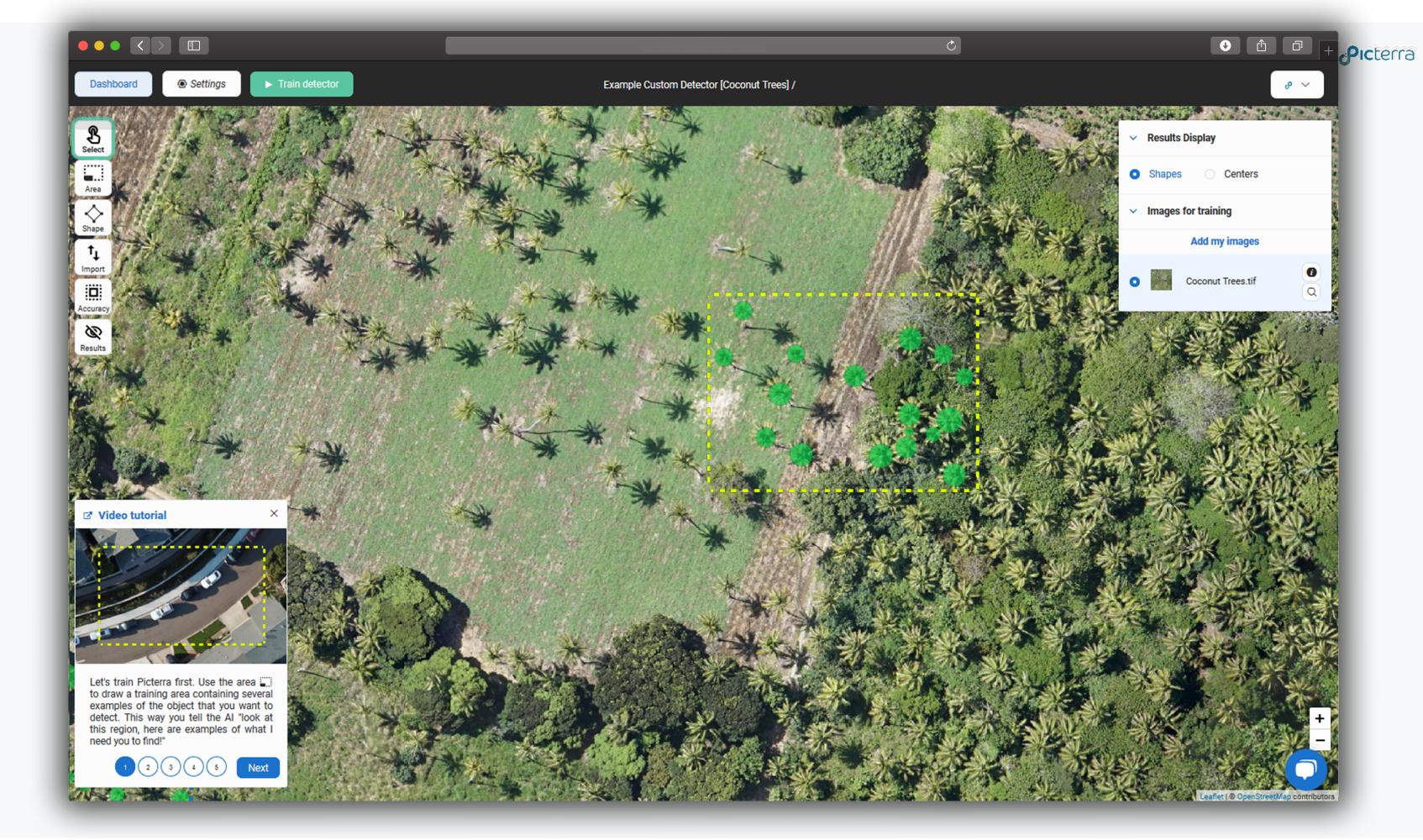
USER

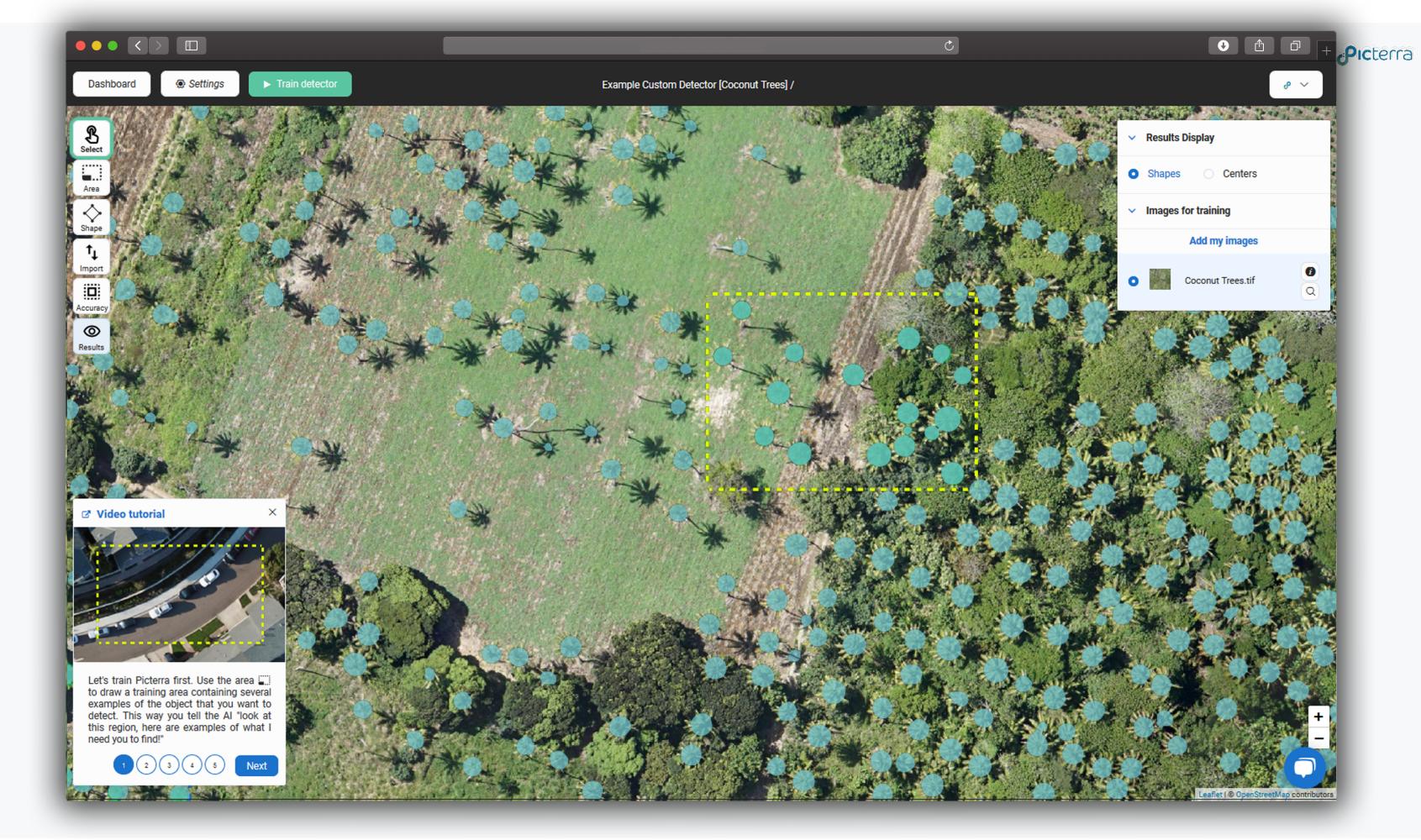
MODEL INPUT

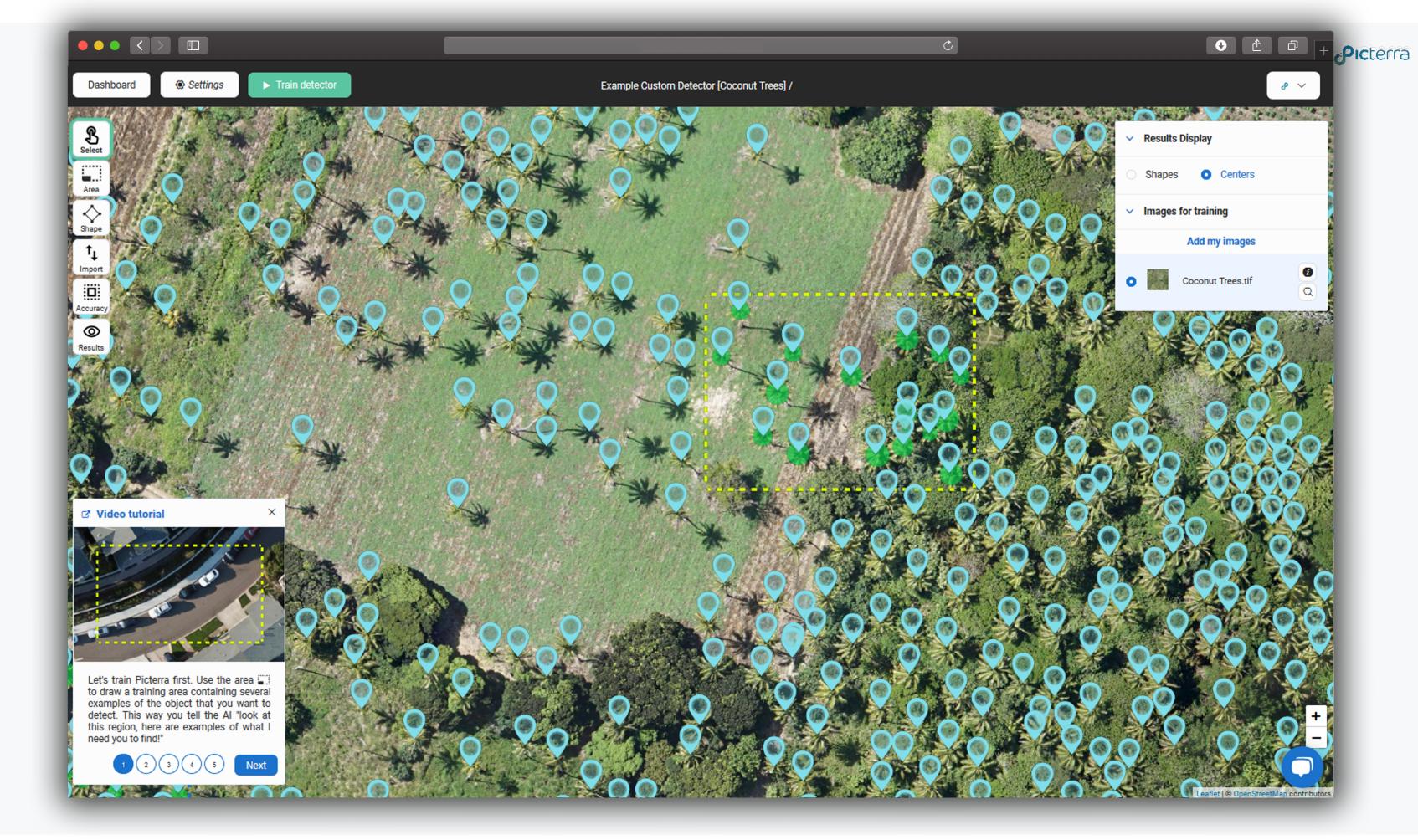
ENABLED BY LOW-SHOT LEARNING



## IF YOU CAN SEE IT AI CAN LEARN TO FIND IT







#### COUNTRY-SCALE DETECTION WITH ..... TRAINING ANNOTATIONS

- Detections of slurry tanks nearby 34'000 farms over all Denmark
- ~1 TB of imagery at 25cm over 34'000 detection areas
- Detector trained to recognize tanks and discriminate covered and uncovered ones







# Validation Area Ground Truths 100 200 400 500 -

#### les·so picterra

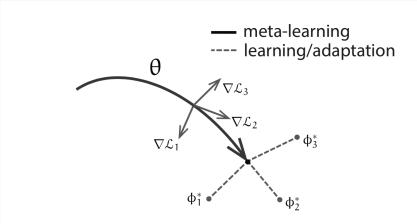


Figure 1: Illustrative diagram of our model-agnostic meta-learning algorithm (MAML), which optimizes for a representation  $\theta$  that can quickly adapt to new tasks.

#### Requirements:

- Preserve user interaction
- Detection of custom objects

#### Approach:

 Meta-Learning training scheme (vs. data augmentation approaches)

#### Algorithm 1 Reptile (serial version)

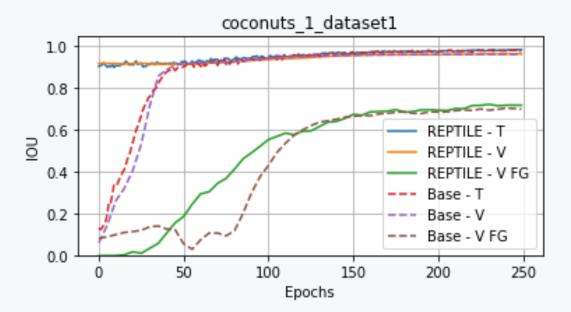
Initialize  $\phi$ , the vector of initial parameters

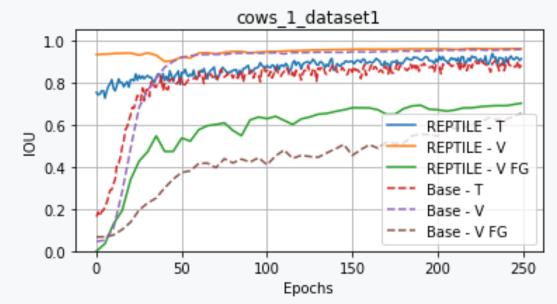
for iteration =  $1, 2, \dots$  do

Sample task  $\tau$ , corresponding to loss  $L_{\tau}$  on weight vectors  $\widetilde{\phi}$ Compute  $\widetilde{\phi} = U_{\tau}^{k}(\phi)$ , denoting k steps of SGD or Adam Update  $\phi \leftarrow \phi + \epsilon(\widetilde{\phi} - \phi)$ 

end for

Alex Nichol, Joshua Achiam and John Schulman. On First-Order Meta-Learning Algorithms. arXiv:1803.02999





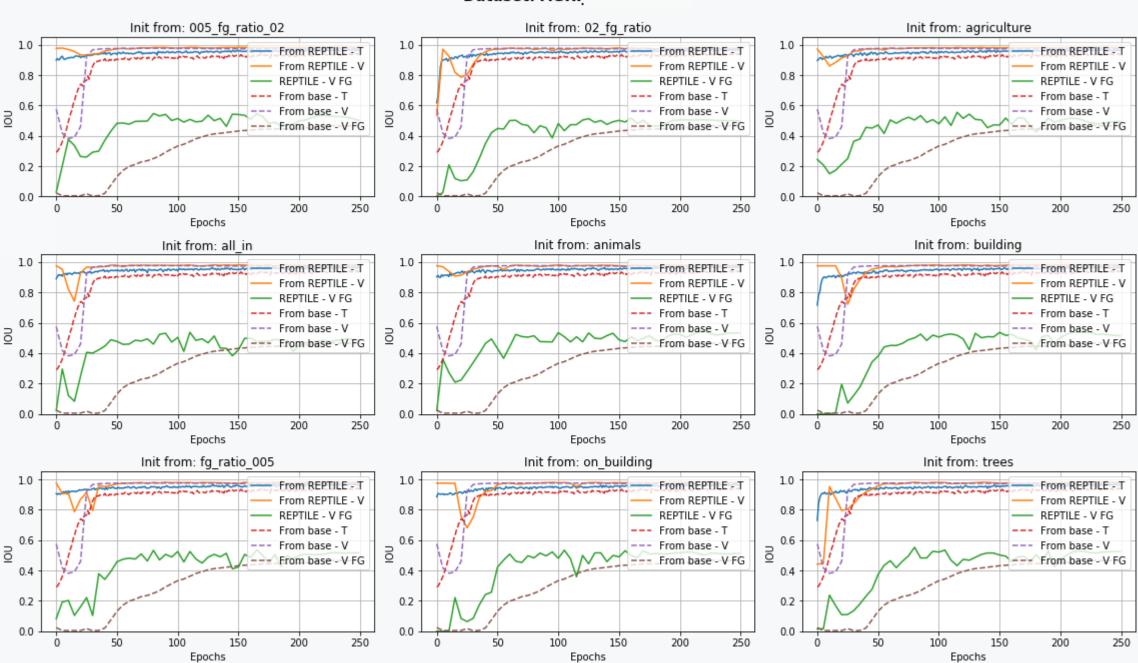




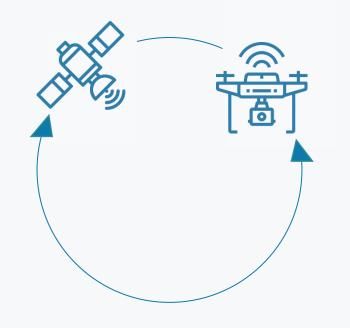


#### Reptile training: does grouping data matter?





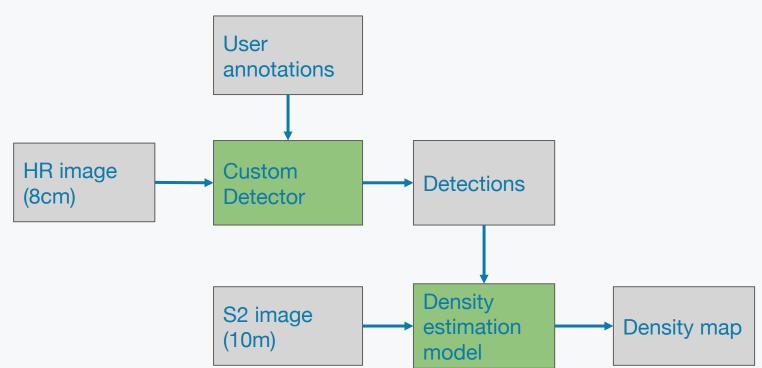




How to detect object at sub-pixel level (too low resolution imagery)? => Learn to estimate object density on each pixel

#### Use case:

- VHR aerial imagery (<10cm) & Sentinel-2 imagery (10m)</li>
- Plantation density estimation
- Density = count of objects contained in a pixel

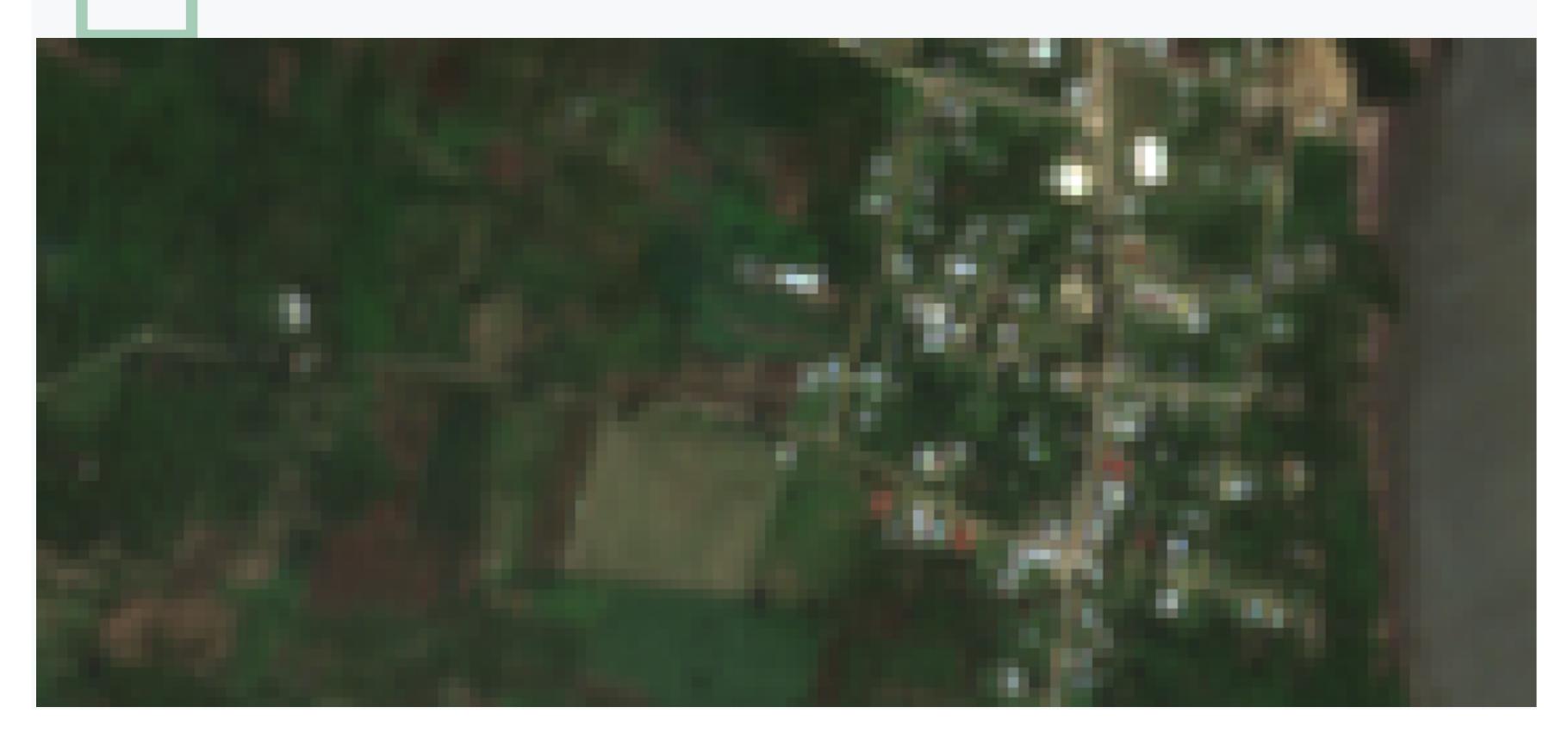




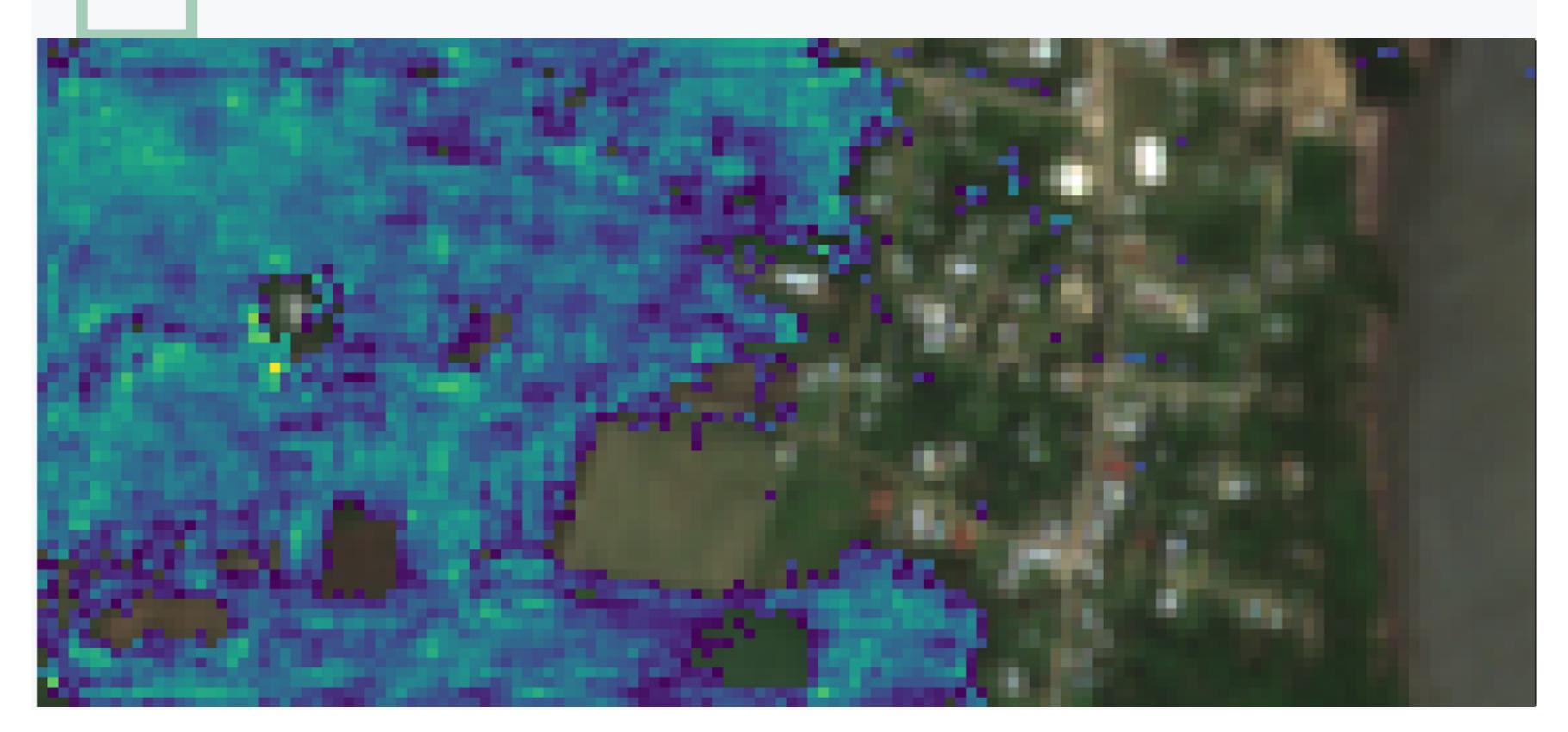




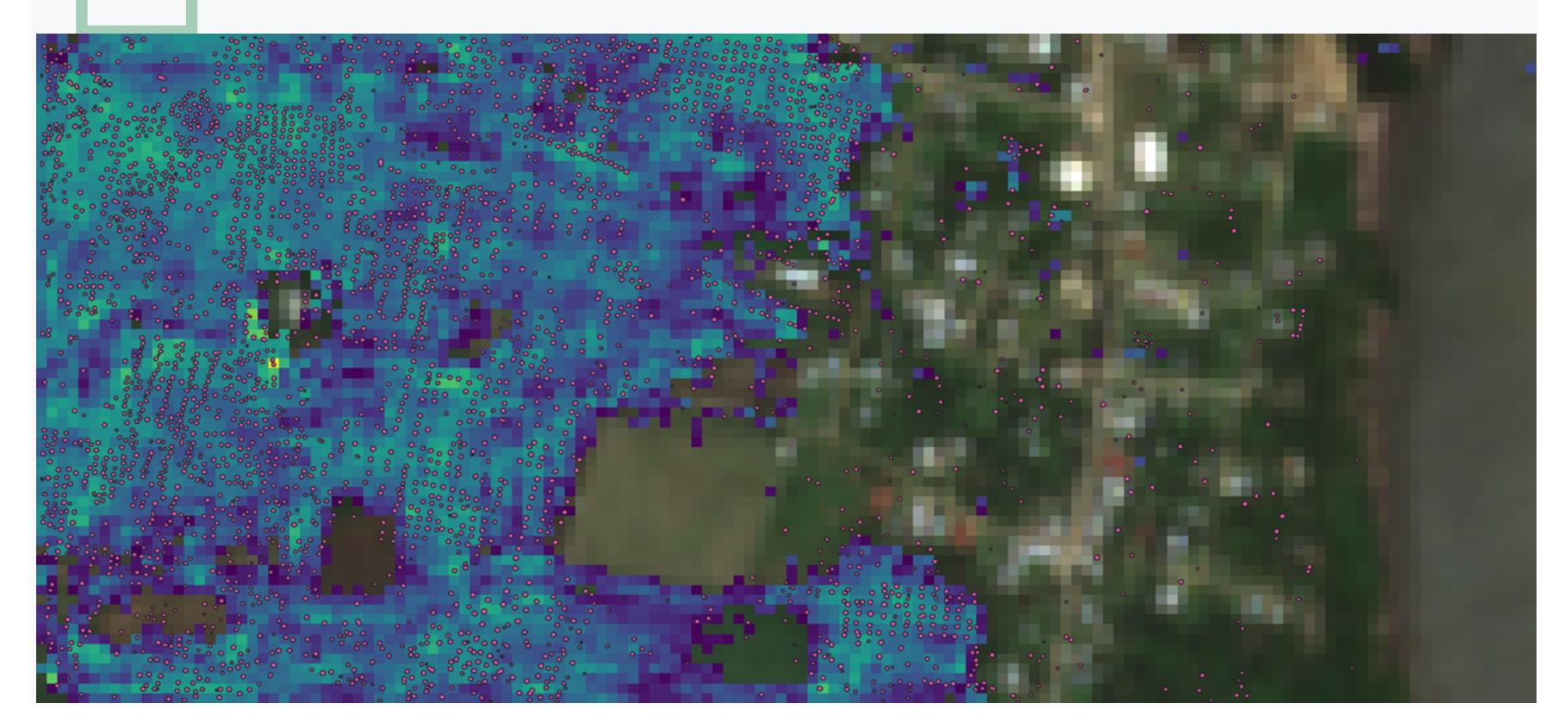














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**Get Started**