

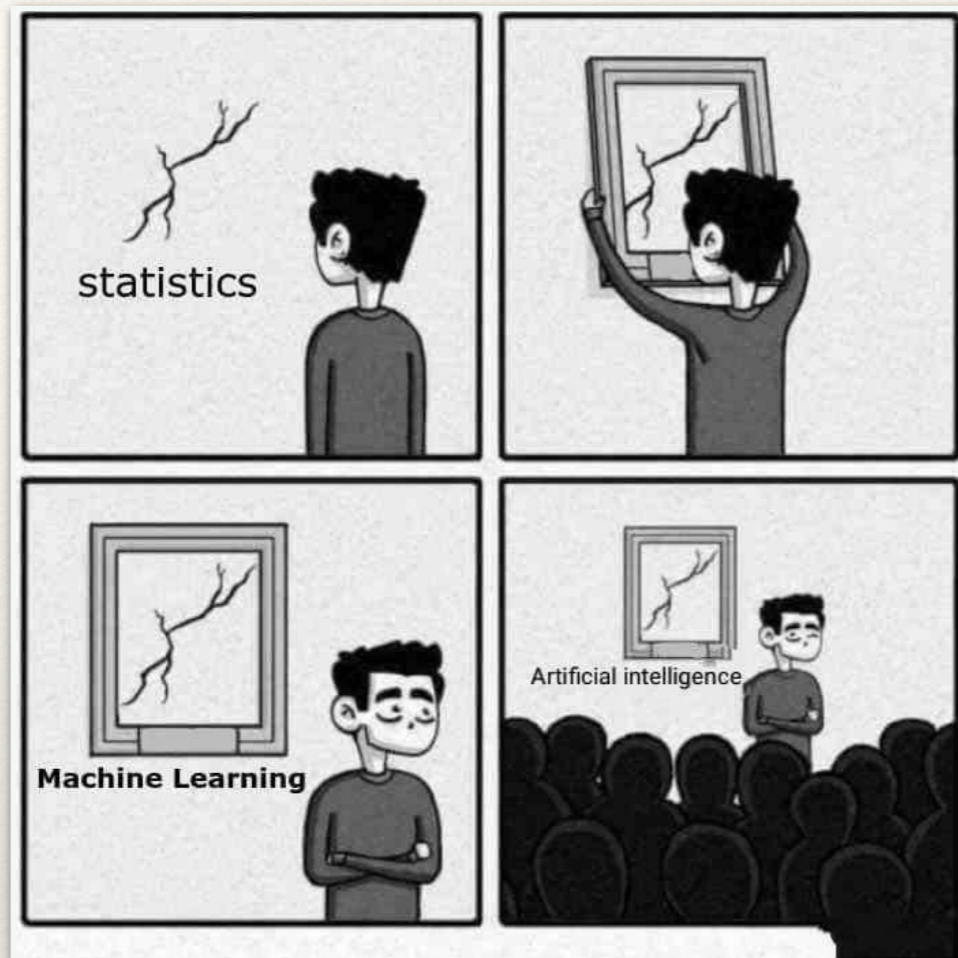
# DeepMoD **Model discovery with neural networks**

Gert-Jan Both, Remy Kusters

CRI Research, Université Paris Descartes, Paris, France



# AI, ML and statistics



@sandserif

Main criticisms ...

ML provides uninterpretable solutions

Statistical ML vs. Symbolic ML

## Goal:

Develop tools to discover **interpretable** models for quantitative science

## Approach:

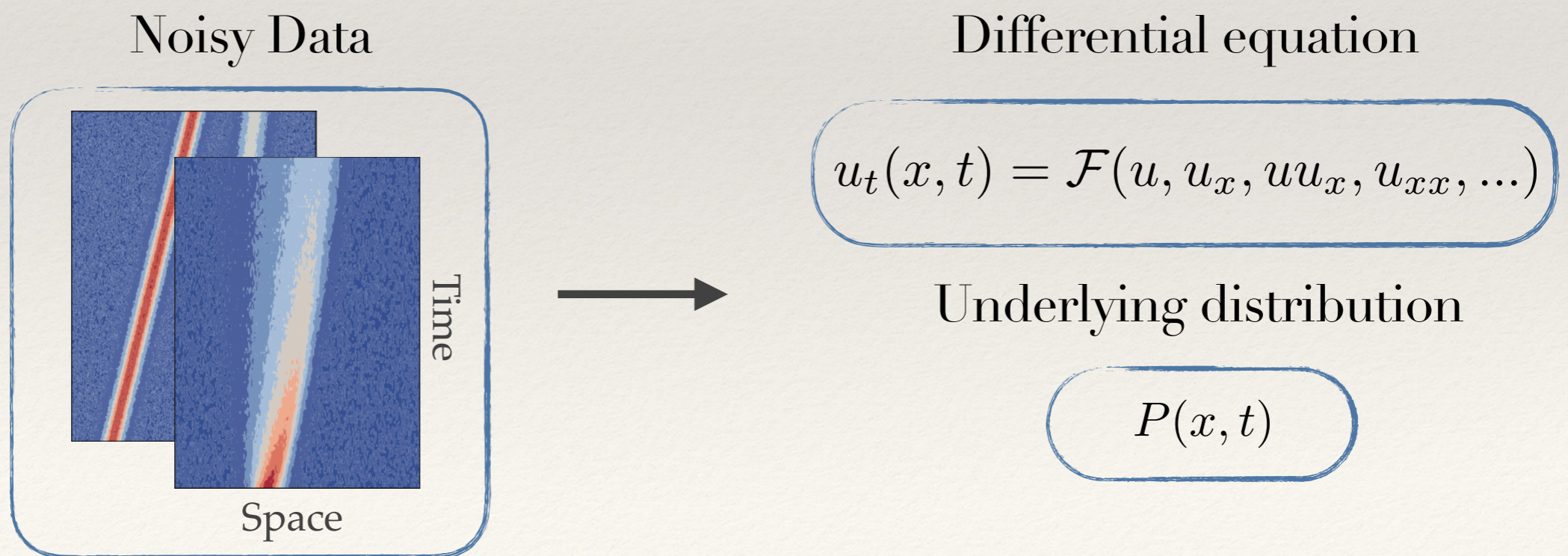
Combine the **statistical power of neural networks** with the **symbolic power of regression**

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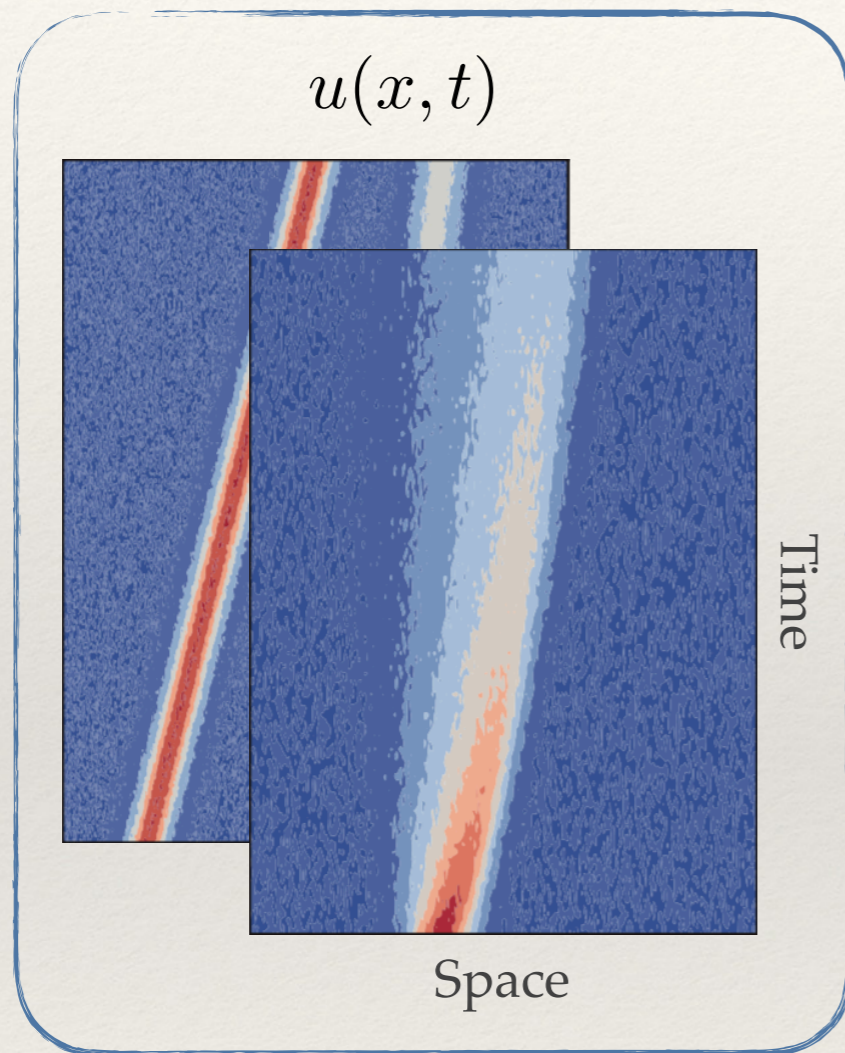
Combine the **statistical power of neural networks** with the **symbolic power of regression**



# DeepMoD

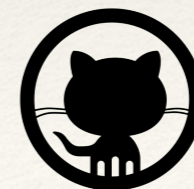
Model discovery  
with neural networks

Noisy Data



Analytic solution

$$u_t(x, t) = \mathcal{F}(u, u_x, uu_x, u_{xx}, \dots)$$

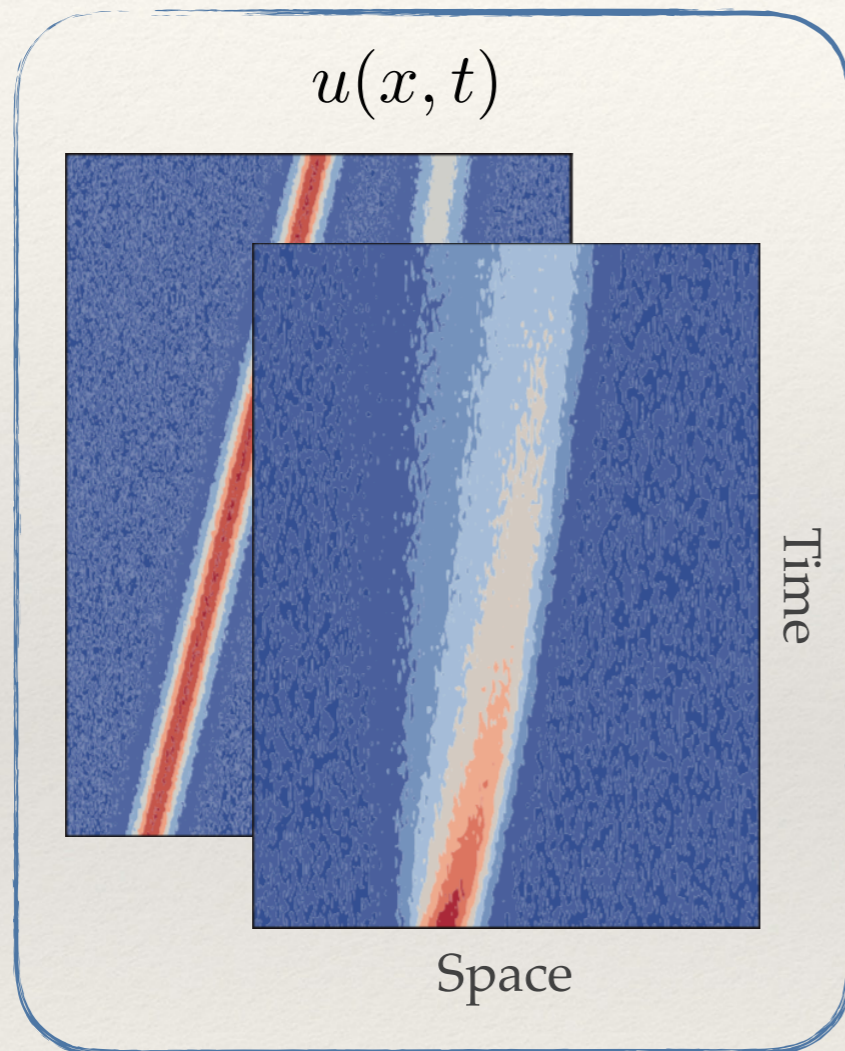


Code available:  
[github.com/PhIMaL](https://github.com/PhIMaL)

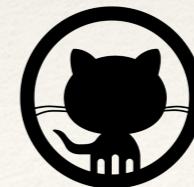
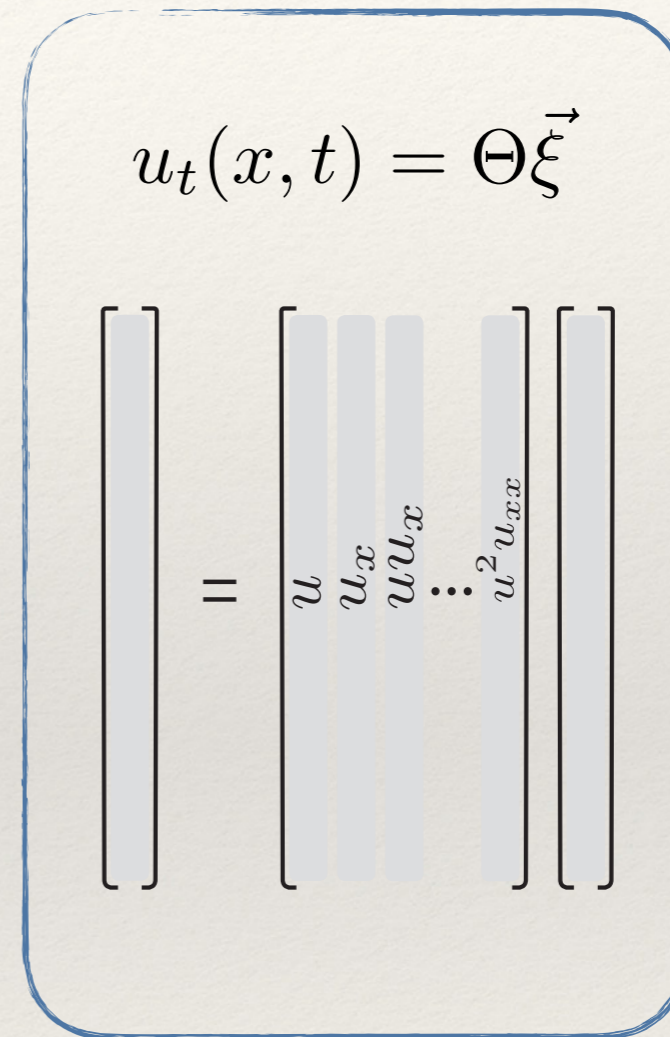
# DeepMoD

Model discovery  
with neural networks

Noisy Data



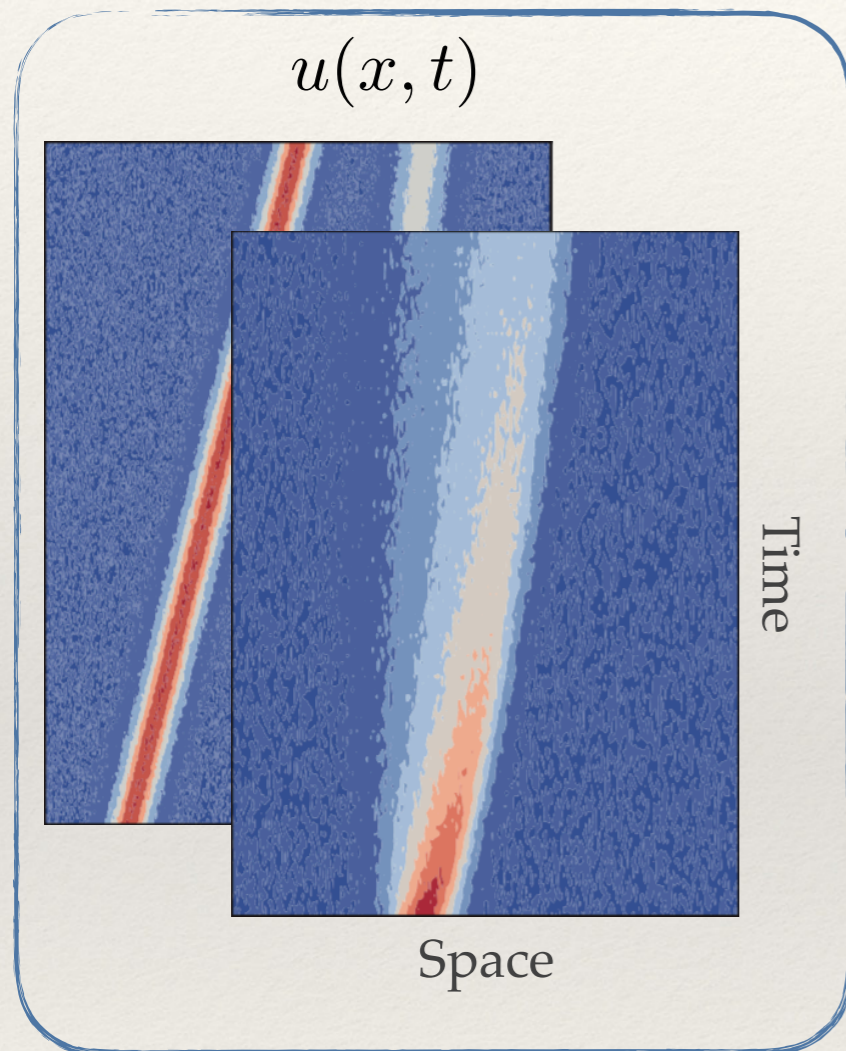
Solution



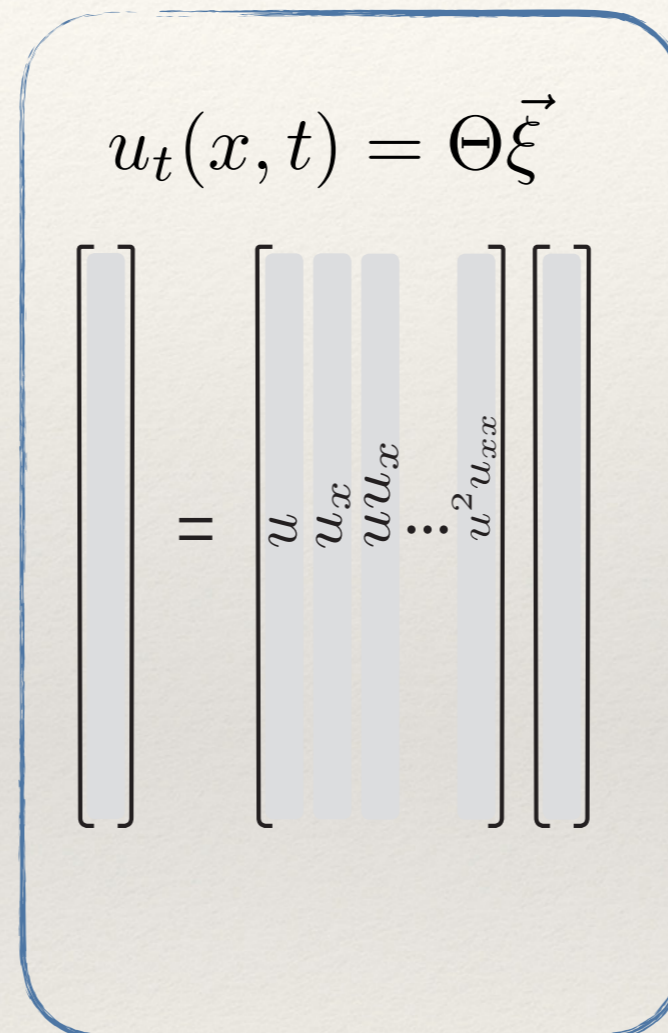
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# DeepMoD Model discovery with neural networks

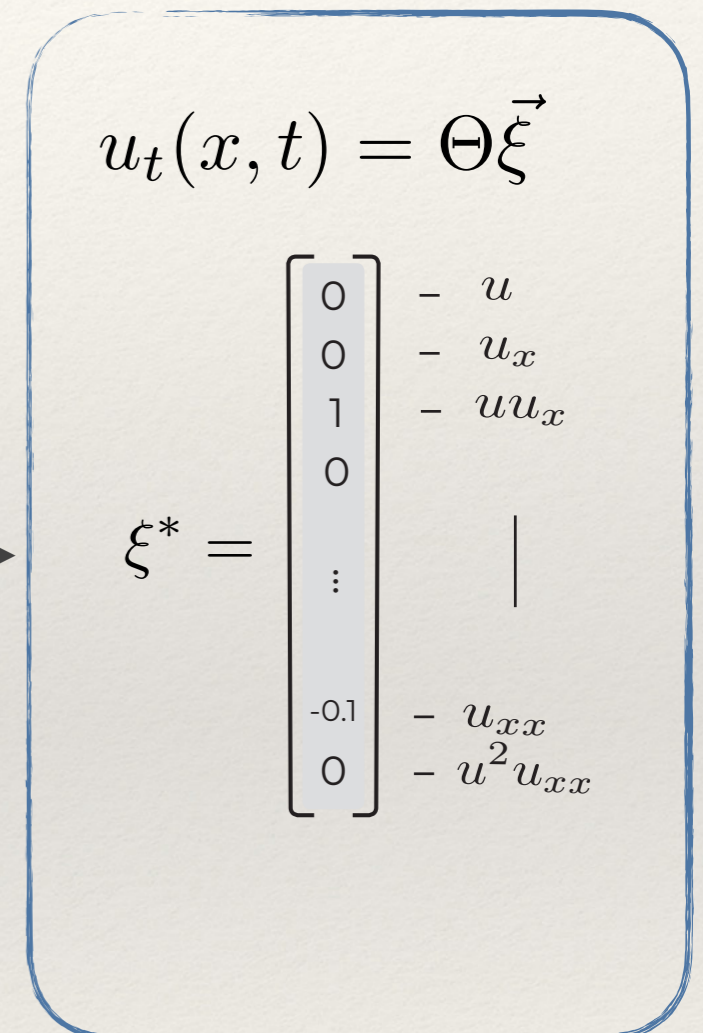
Noisy Data



Regression



Solution

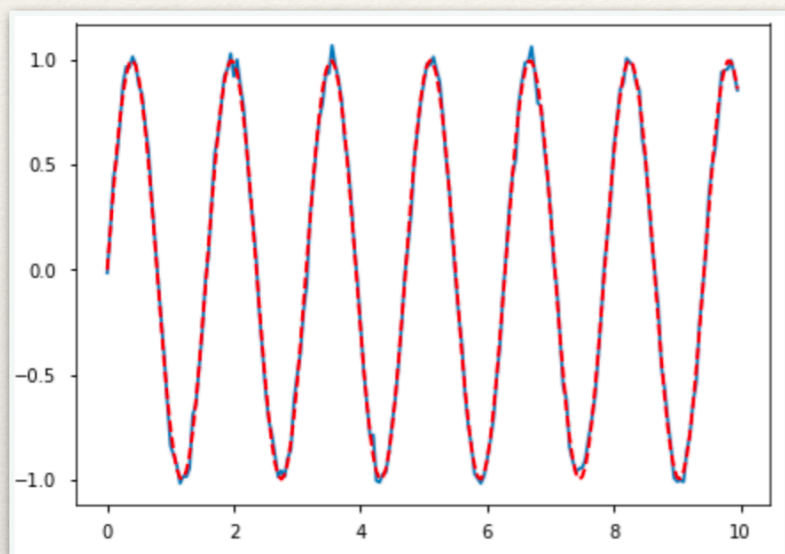


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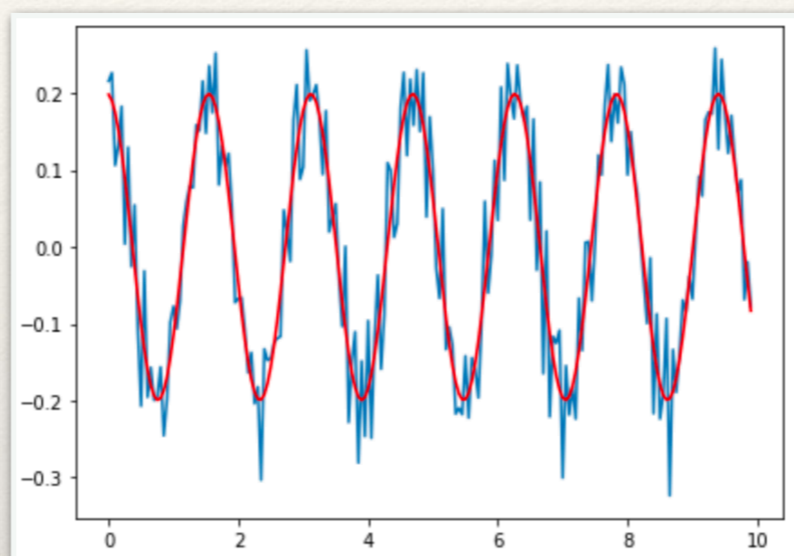
# Why does it fail with noise?

5% white noise ...

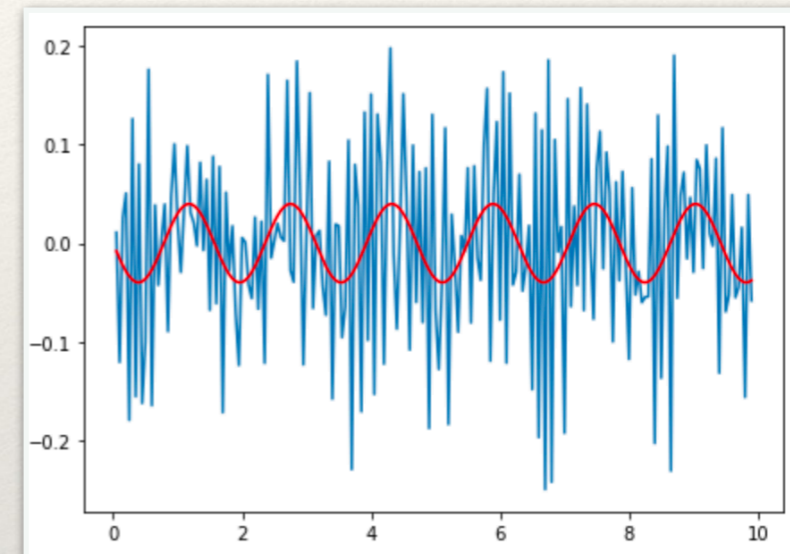
$u(x)$



$u_x(x)$



$u_{xx}(x)$



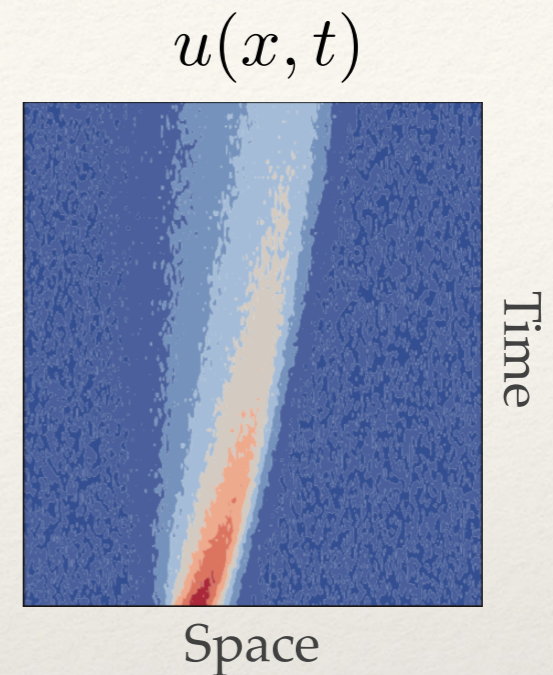
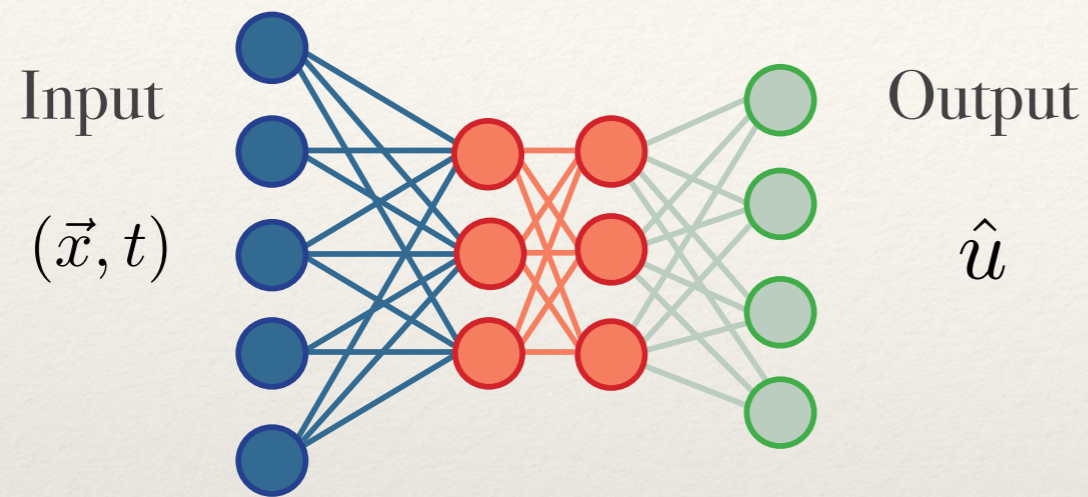
$$\Theta = \begin{pmatrix} \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ u & u_x & u_x u & u_{xx} & u_{xx} u & u_{xx} u_x & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \end{pmatrix}$$

**Numerically** calculating library impossible ...



# Our approach ...

## The Neural Network



Construct the library w.r.t. **the inferred solution**

$$\Theta = \begin{pmatrix} \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \\ \hat{u} & \hat{u}_x & \hat{u}_x \hat{u} & \hat{u}_{xx} & \hat{u}_{xx} \hat{u} & \hat{u}_{xx} \hat{u}_x & \cdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \end{pmatrix}$$

Include the **regression task** within the neural network

# How do we train a neural network

Optimise loss function:

$$\mathcal{L} = \mathcal{L}_{MSE} + \mathcal{L}_{Reg} + \mathcal{L}_{L_1}$$

Approximate the data as good as possible ...

Learn the mapping  
 $(\vec{x}, t) \rightarrow \vec{u}$

$$\mathcal{L}_{MSE} = \frac{1}{N} \sum_{i=1}^N |u(\{x, t\}_i) - \hat{u}_i|^2$$

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Discover the differential equation

Regression  
(Seek the PDE)

$$\mathcal{L}_{Reg} = \frac{1}{N} \sum_{i=1}^N |\Theta_{ij} \xi_j - \partial_t \hat{u}_i|^2$$

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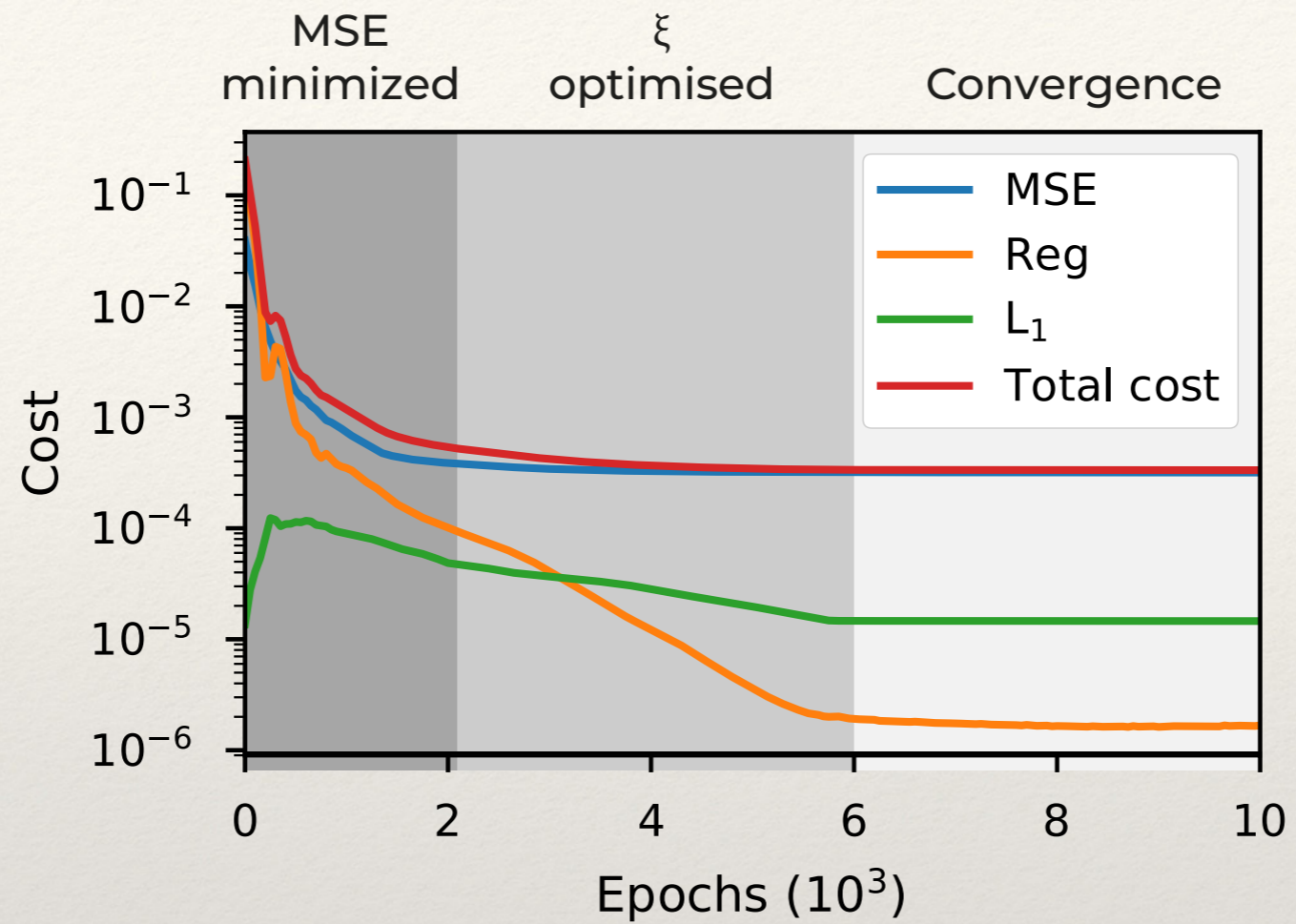
$$\mathcal{L}_{Reg} = \frac{1}{N} \sum_{i=1}^N |\Theta_{ij} \xi_j - \partial_t \hat{u}_i|^2$$

Promoting sparsity

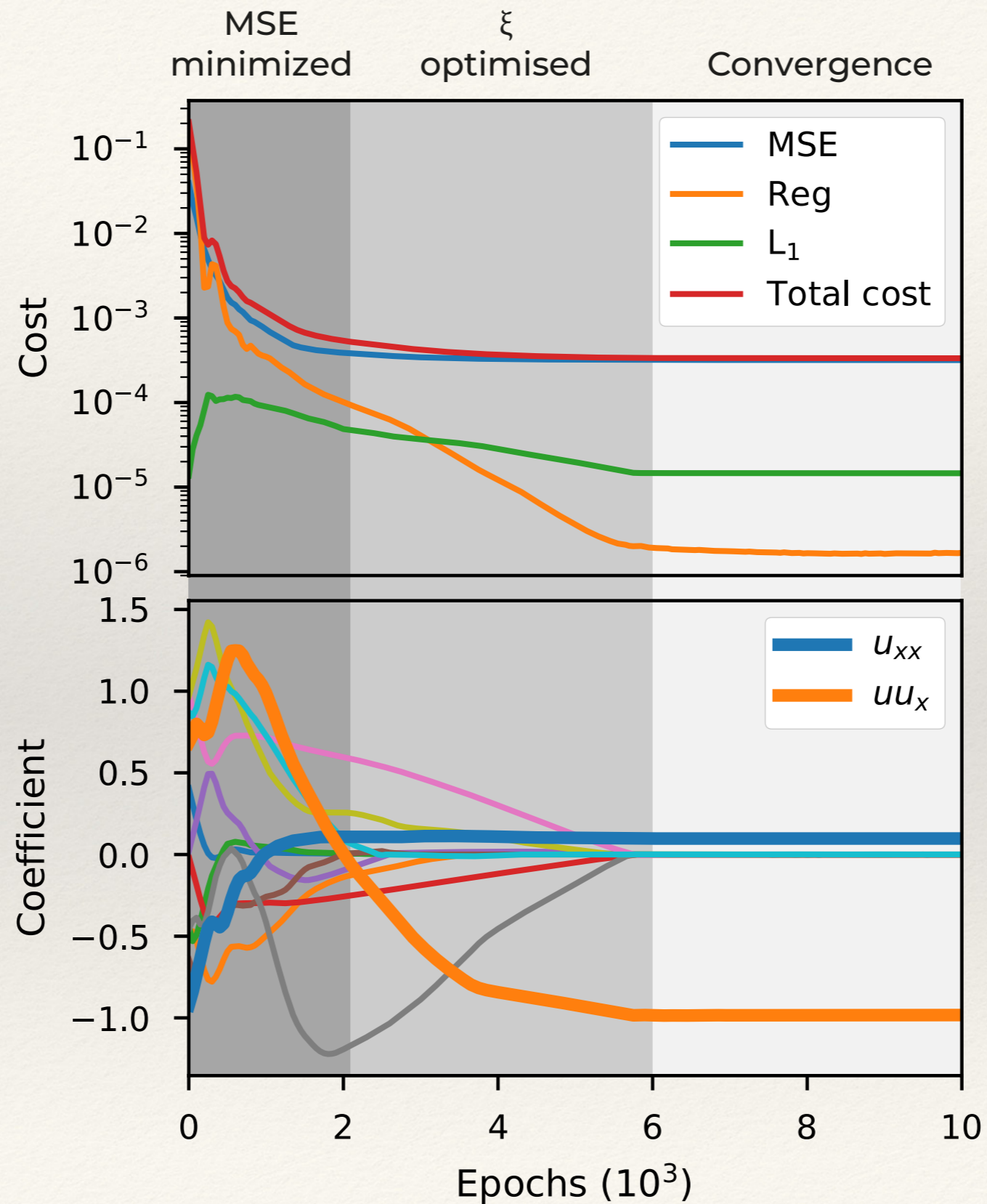
L1 Penalty

$$\mathcal{L}_{L_1} = \lambda \sum_{i=2}^M |\xi^i|$$

# Training the neural network



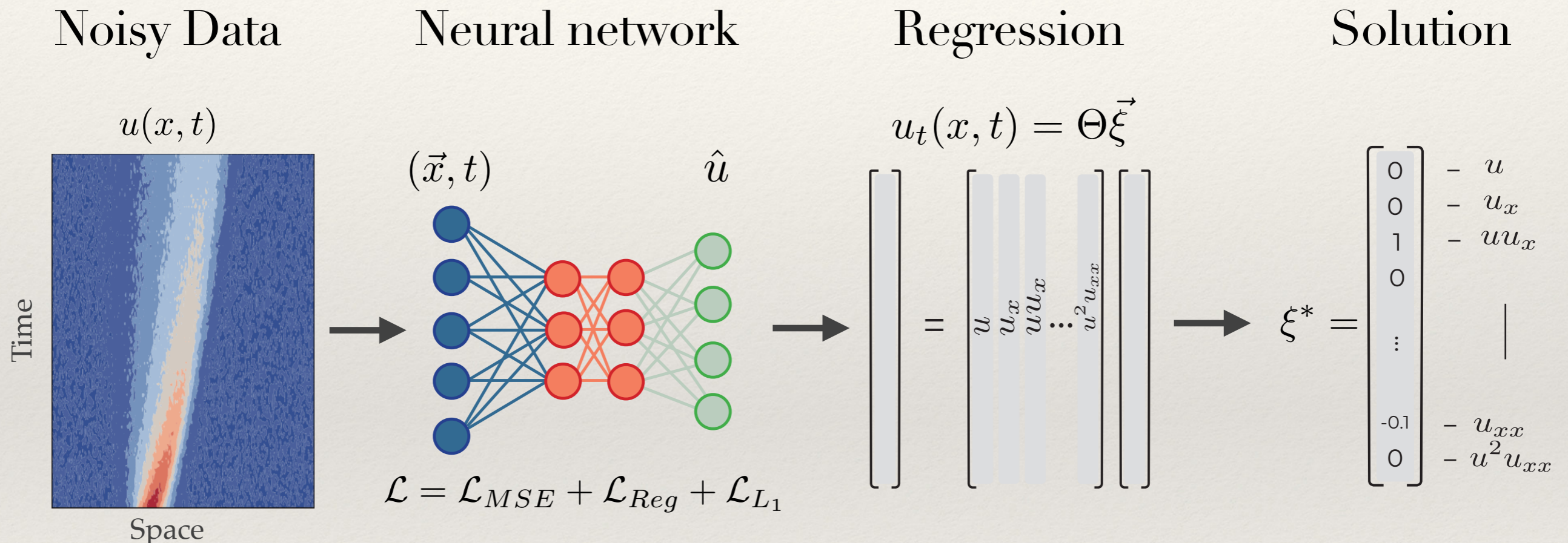
# Training the coefficient vector



$$u_t(x, t) = \Theta \vec{\xi}$$

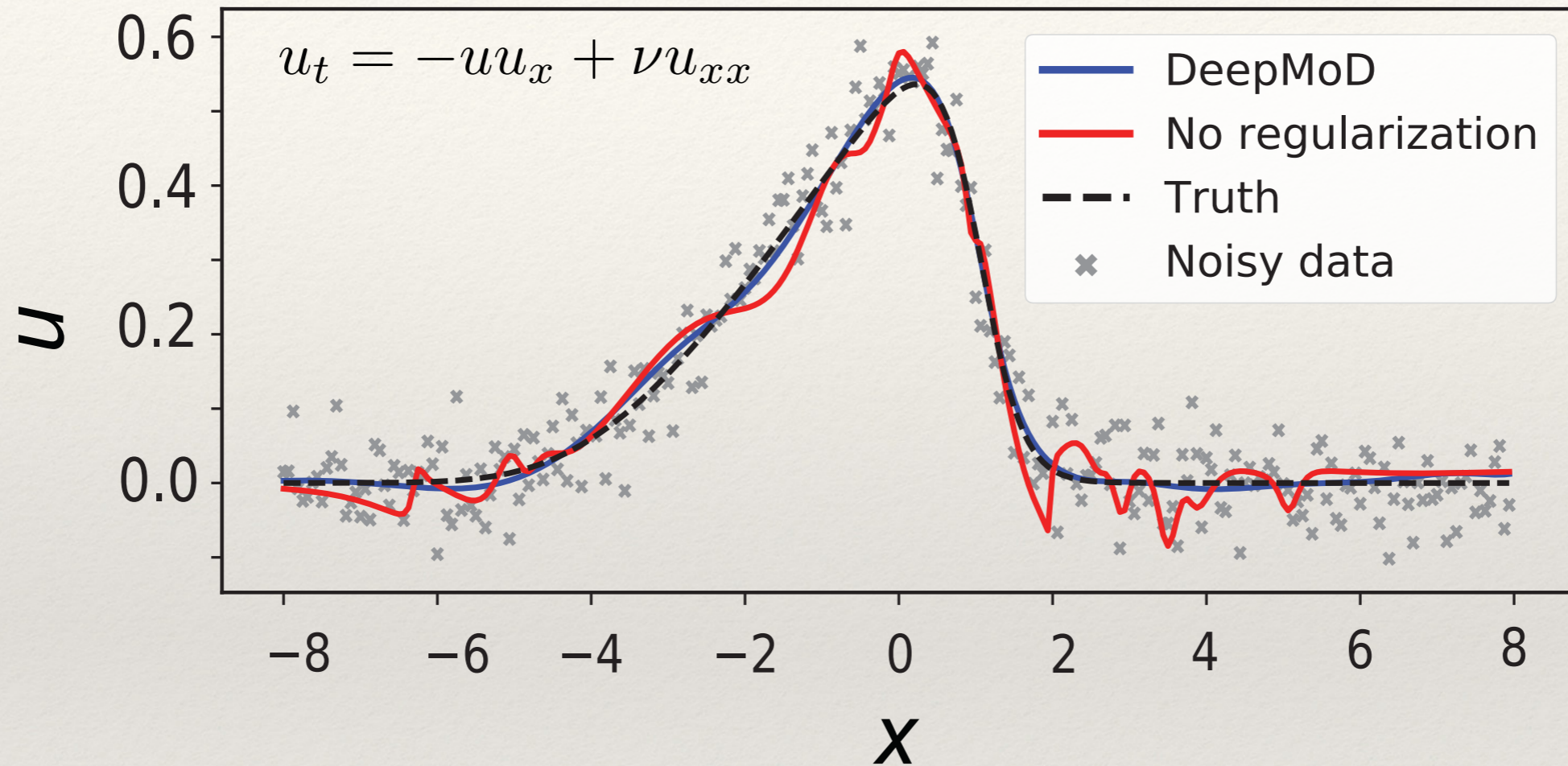
$$\vec{\xi}^* = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ \vdots \\ -0.1 \\ 0 \end{bmatrix} \begin{array}{l} - u \\ - u_x \\ - uu_x \\ | \\ - u_{xx} \\ - u^2 u_{xx} \end{array}$$

# DeepMoD Model discovery with neural networks



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# Why regression inside neural network?





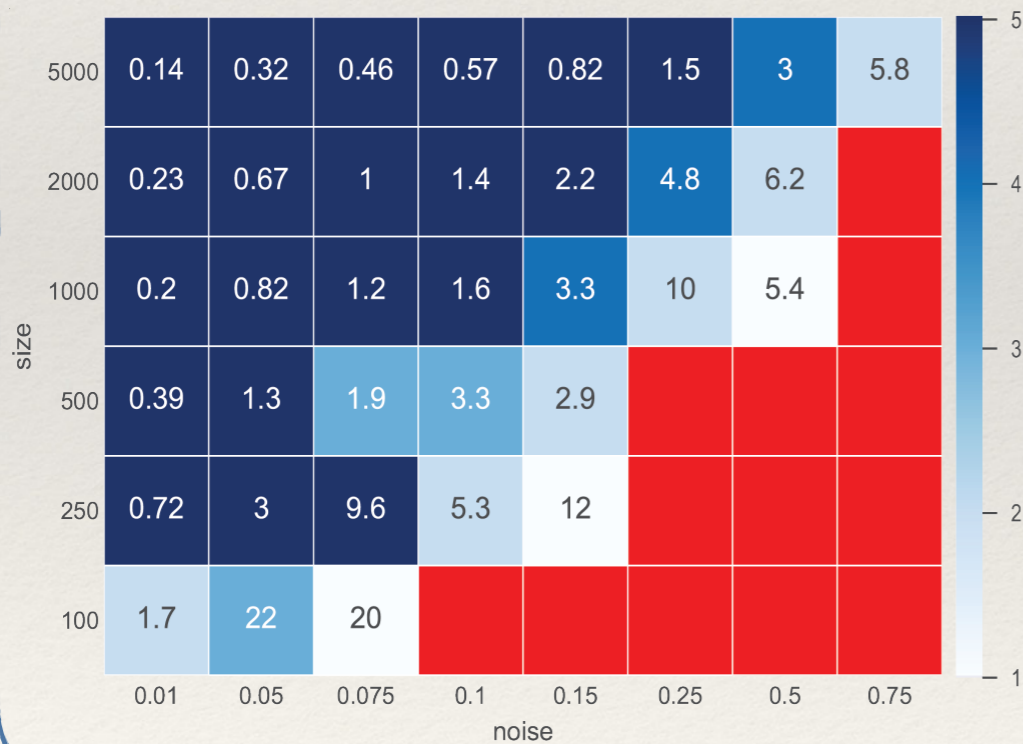
# Applications in physics

## Resilience to Noise/ sampling size

### Burgers' equation

$$u_t = -uu_x + \nu u_{xx}$$

Relative error on coefficients



## Higher order PDEs

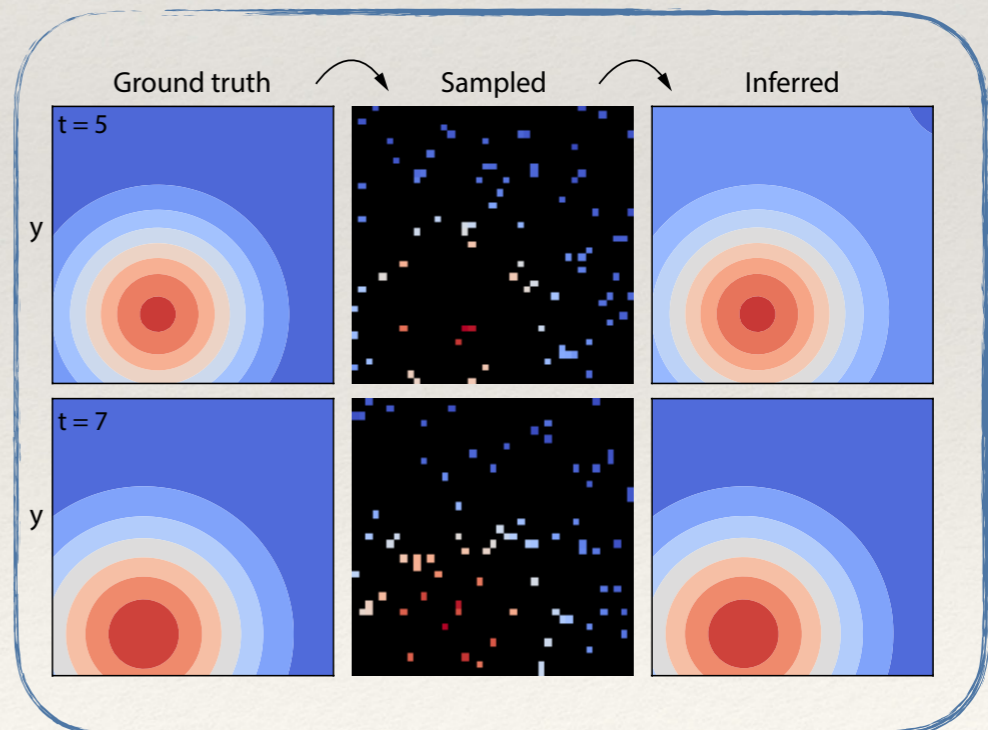
$$u_t = 6uu_x - u_{xxx}$$

## Coupled equations

$$u_t = \nabla \cdot (D_i \nabla u - \xi u \nabla w) \quad u : \text{particle density}$$

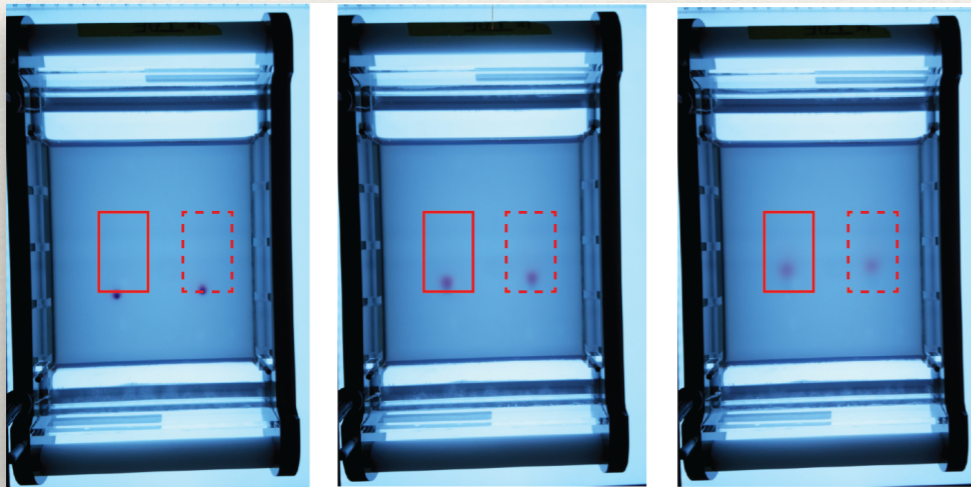
$$w_t = D_w \Delta w - kw + hu \quad w : \text{attractant density}$$

## 2D equations

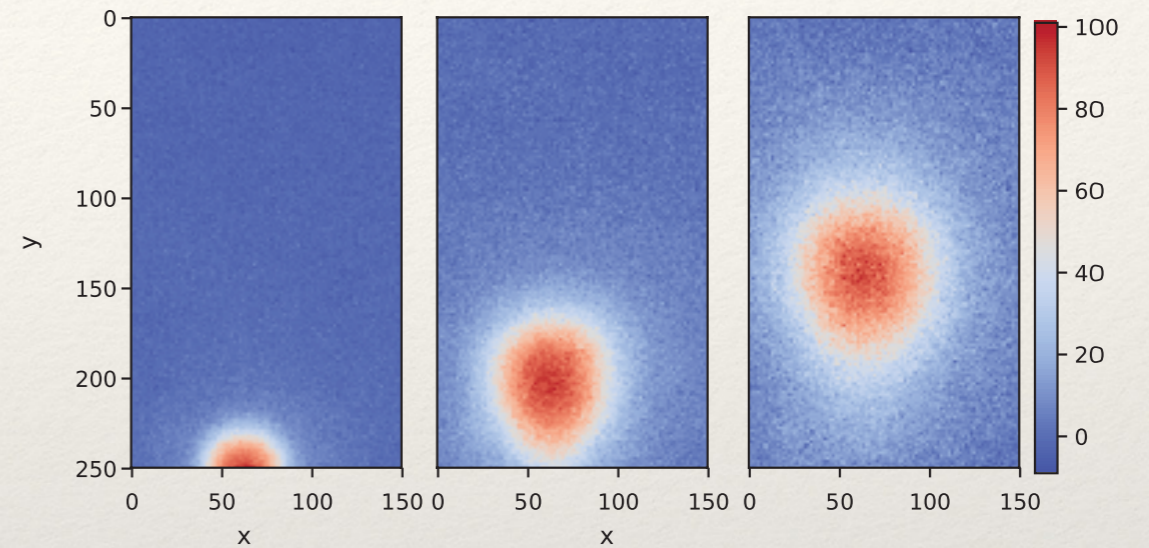


# Apply to real data ...

Raw images



Density field



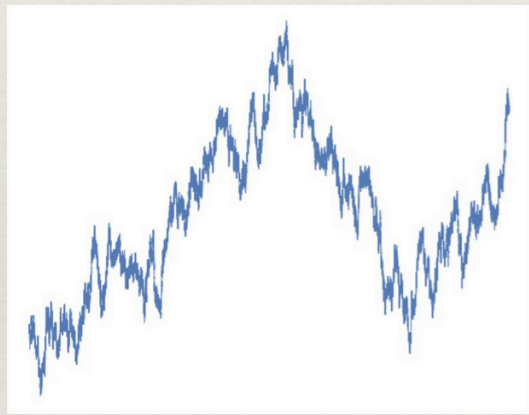
Underlying AD equation

$$u_t = 0.3u_y + 0.01u_{xx} + 0.01u_{yy}$$

Model discovery from **experimental data**

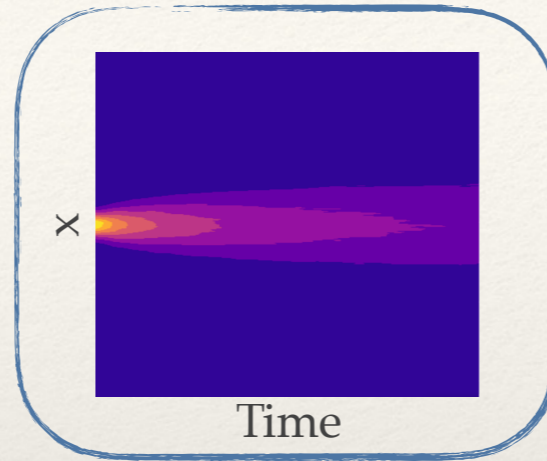
# Single Particle Tracking

Trajectory

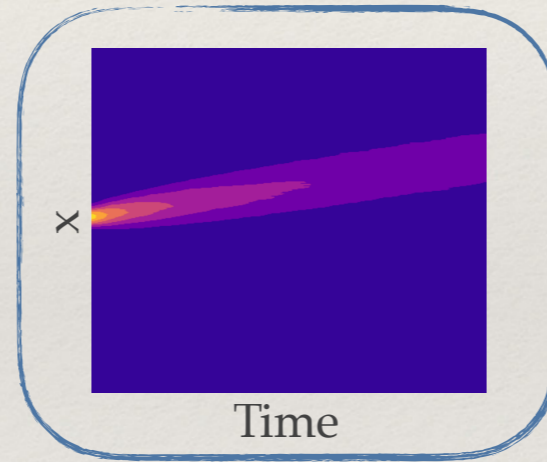


Time

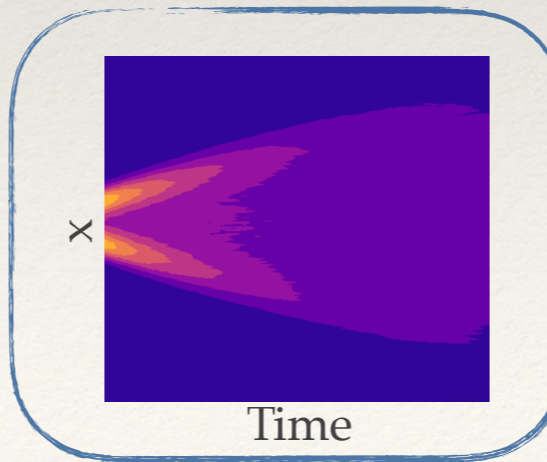
Density  
estimation



Time



Time



Time

Model  
discovery



Random walk

$$u_t = Du_{xx}$$

Advected random walk

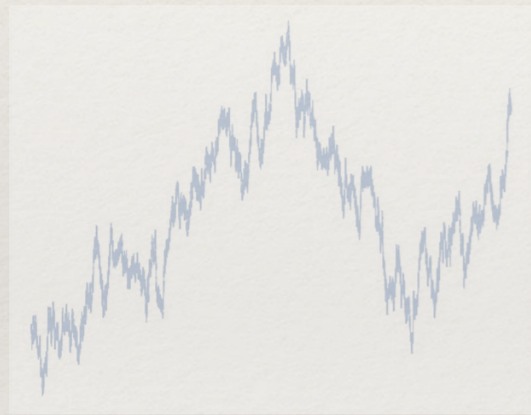
$$u_t = Du_{xx} + v_d u$$

Persistent random walk

$$u_{tt} + \frac{1}{\tau_c} u_t = \nu^2 u_{xx}$$

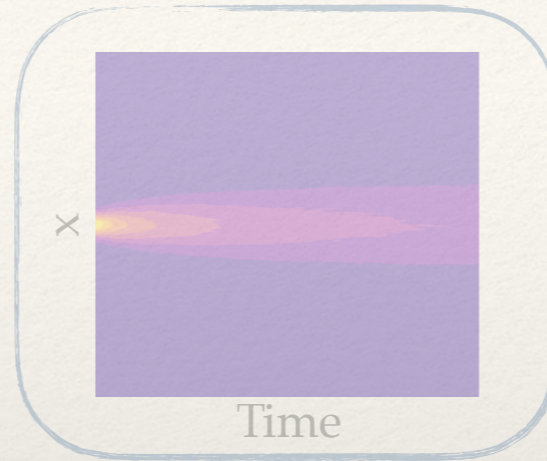
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Trajectory

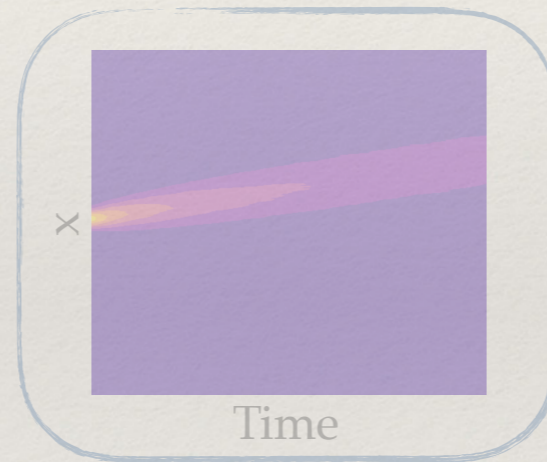


Time

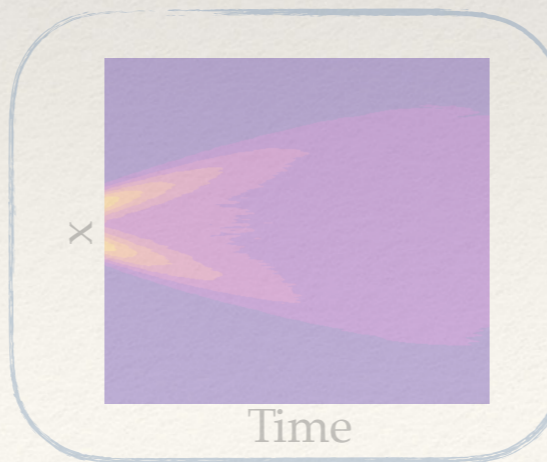
**Density  
estimation**



Time

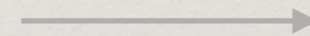


Time



Time

**Model  
discovery**



Random walk

$$u_t = Du_{xx}$$

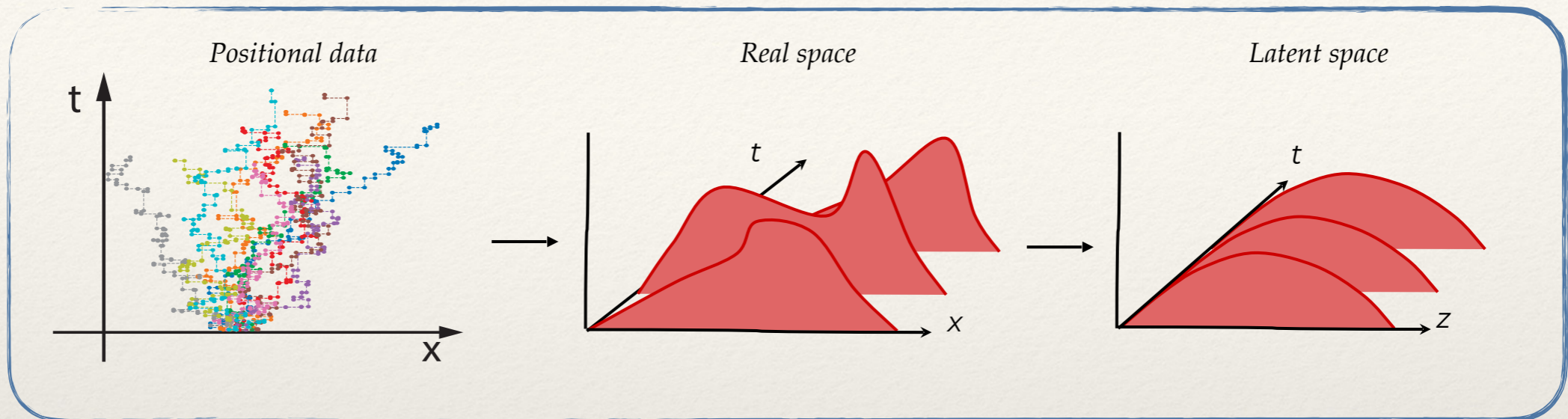
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Persistent random walk

$$u_{tt} + \frac{1}{\tau_c} u_t = \nu^2 u_{xx}$$

# Density estimation: Temporal normalizing flows



Temporal Normalizing Flows (tNFs) extend NFs with a temporal component to estimate a **time-dependent density evolution**

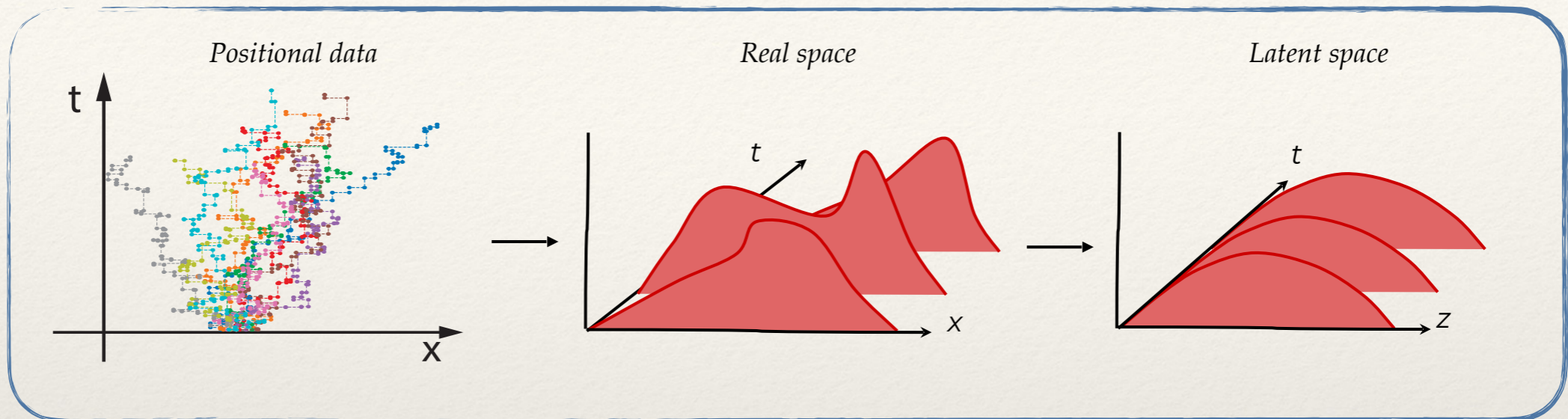


Code available on Github:  
<https://github.com/PhIMaL>



Paper available on arXiv:  
[1912.09092](https://arxiv.org/abs/1912.09092)

# Density estimation: Temporal normalizing flows



Temporal Normalizing Flows (tNFs) extend NFs with a temporal component to estimate a **time-dependent density evolution**

tNFs allow discovery of PDEs with conservation constraints, e.g. Fokker-Planck, ...

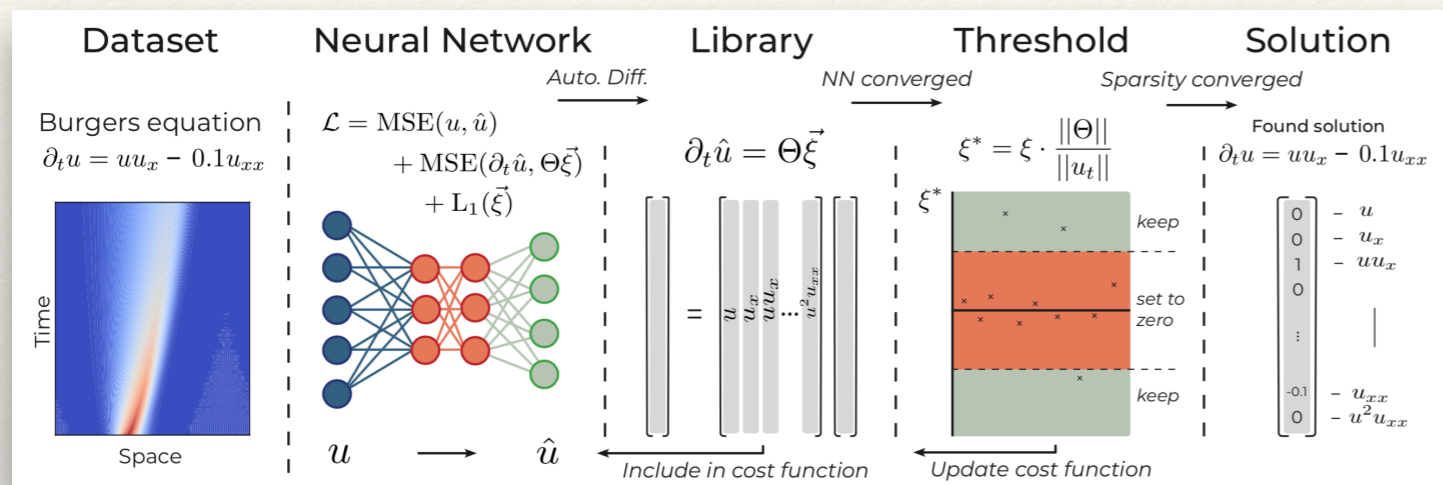


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# DeepMoD Model discovery with neural networks



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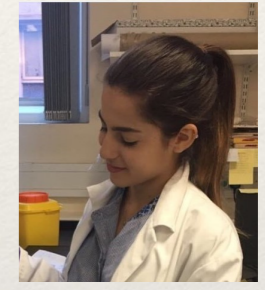
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C. Le Scao  
( Intern )



T. Chrysostomou  
( Intern )



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