



Machine learning for travel mode detection

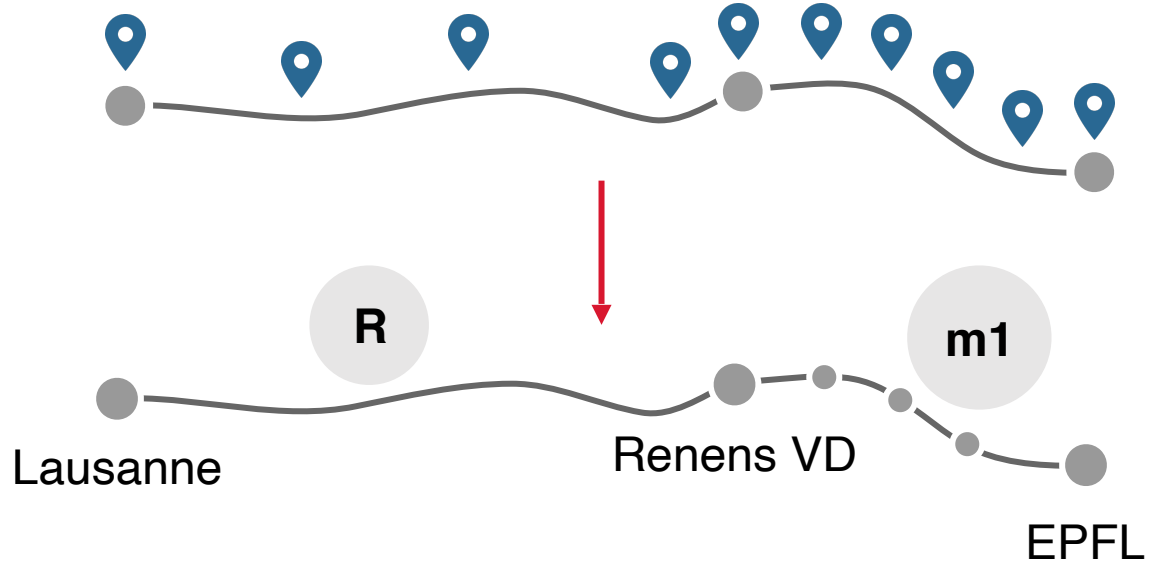
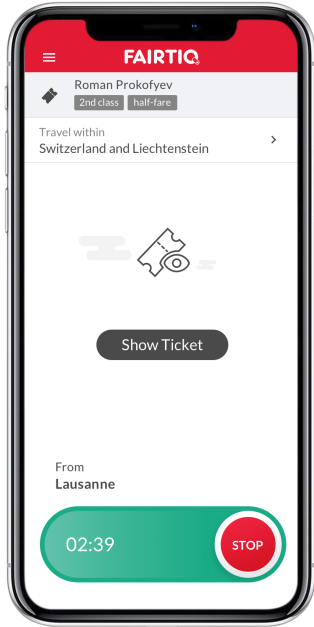
Roman Prokofyev

Co-founder and Chief Scientist

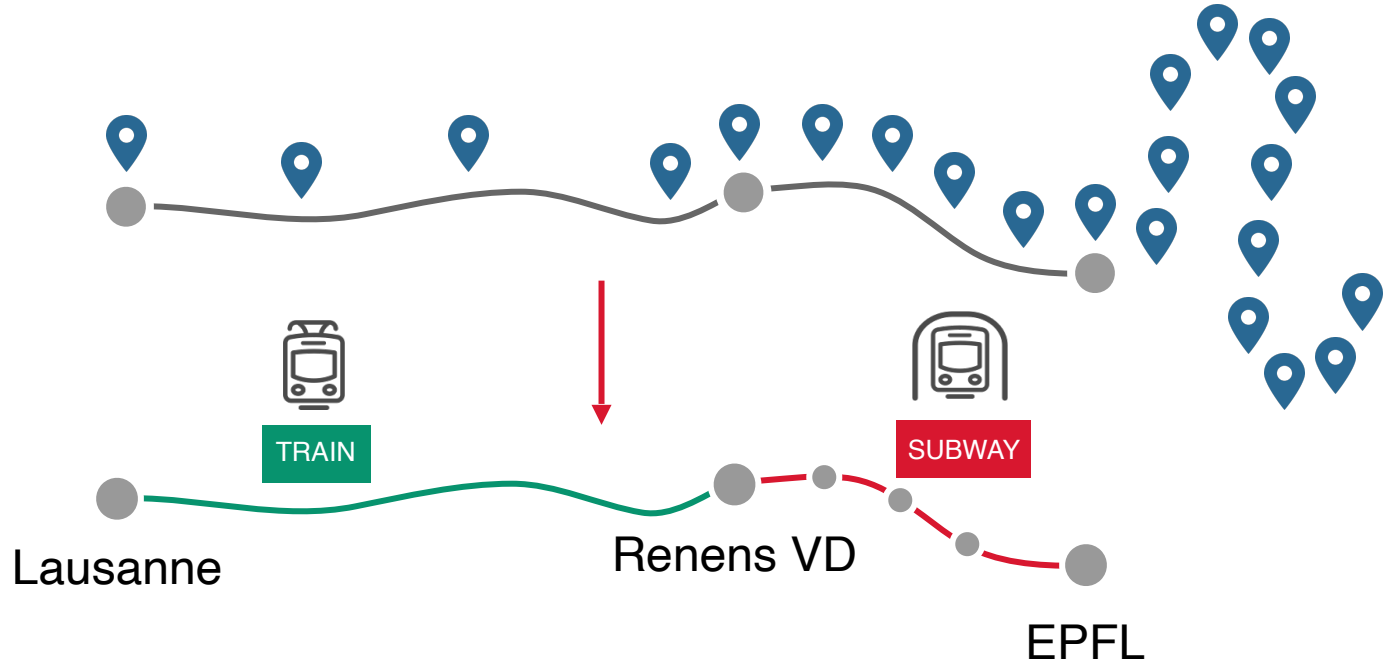
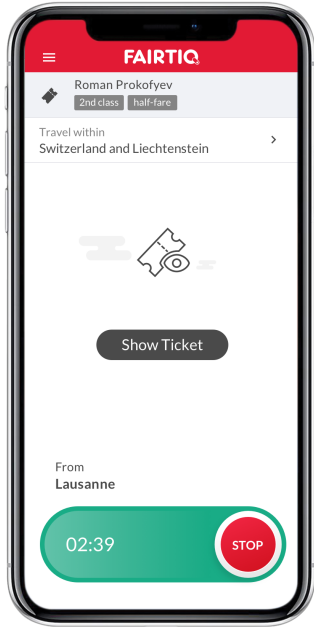
AMLD 2020, EPFL. 28.01.2020



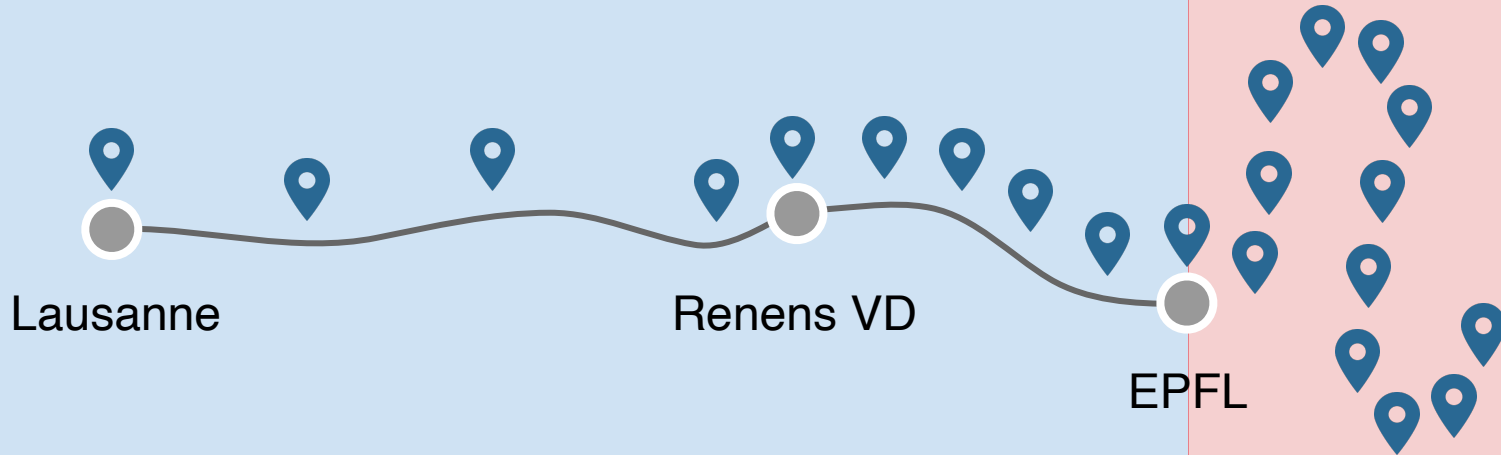
How FAIRTIQ works?



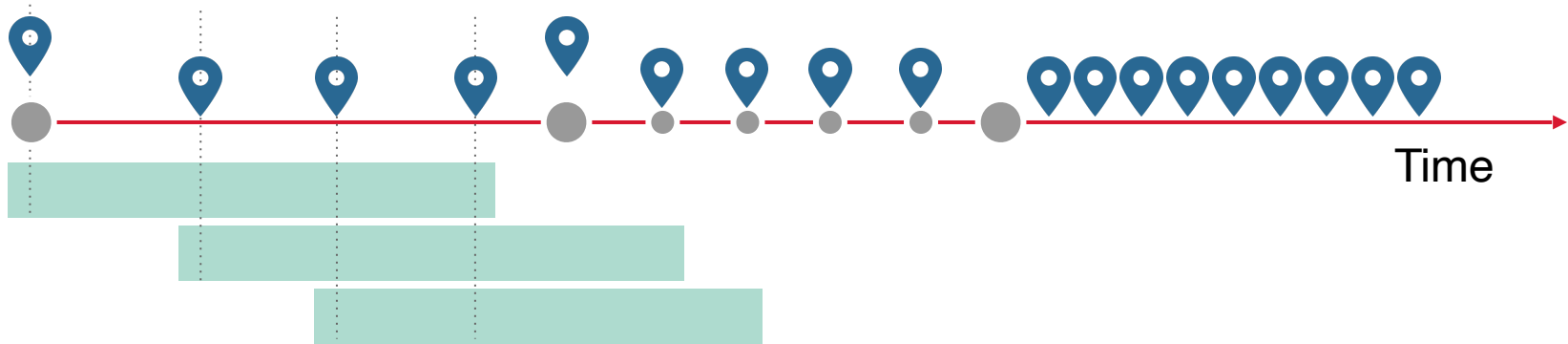
Travel mode detection?



Labelling the data: manually



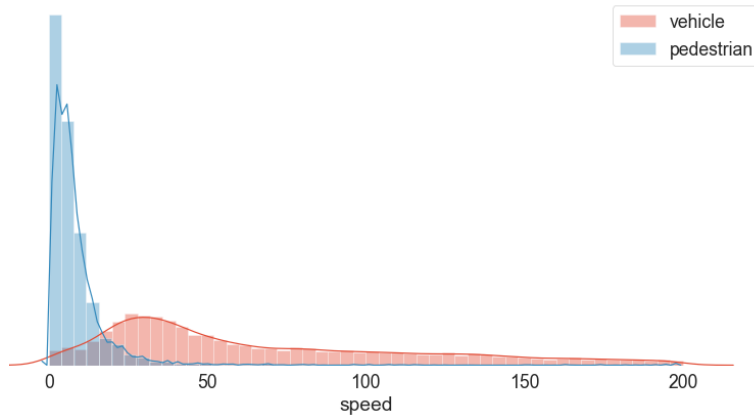
Input: sliding time windows



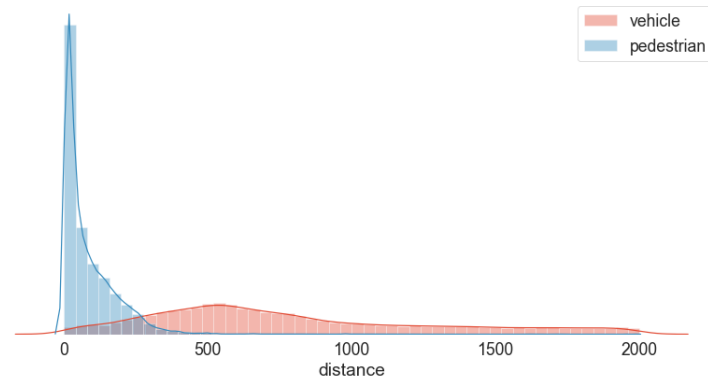
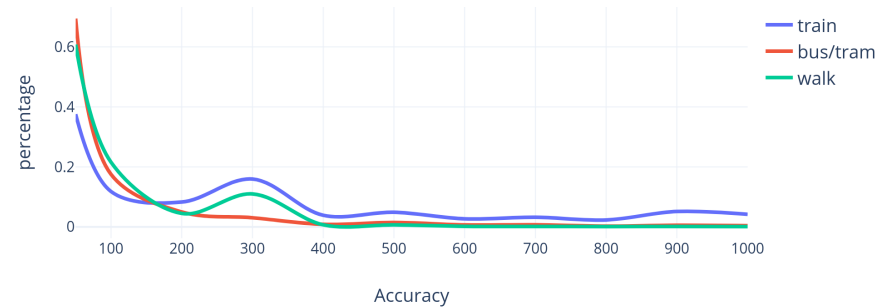
- Min # of locations in a window
- Min duration of a window ~ 3 min.

Features: mostly statistical

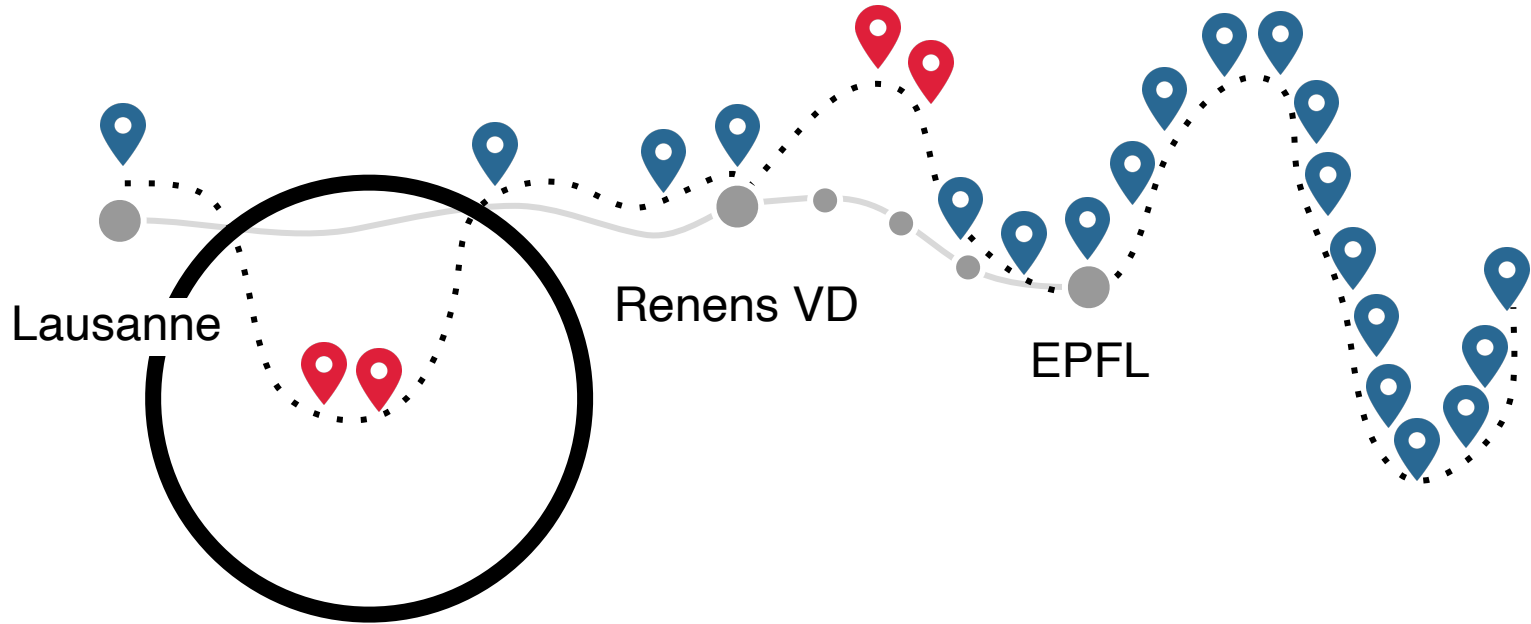
- Speed min/max/percentiles/std/...
- Distances
- Location accuracy



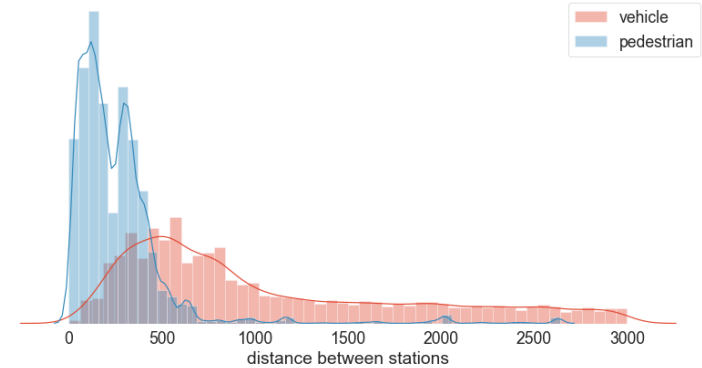
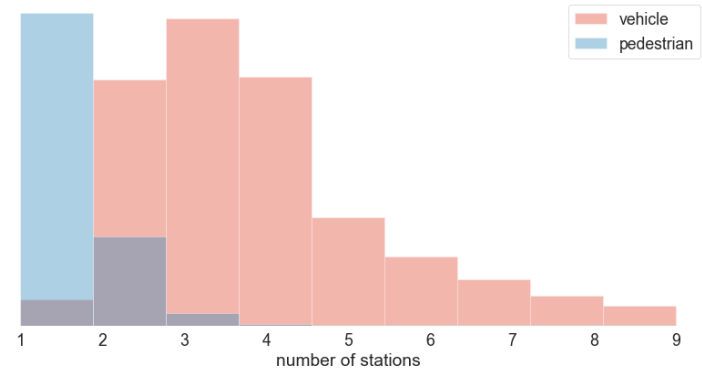
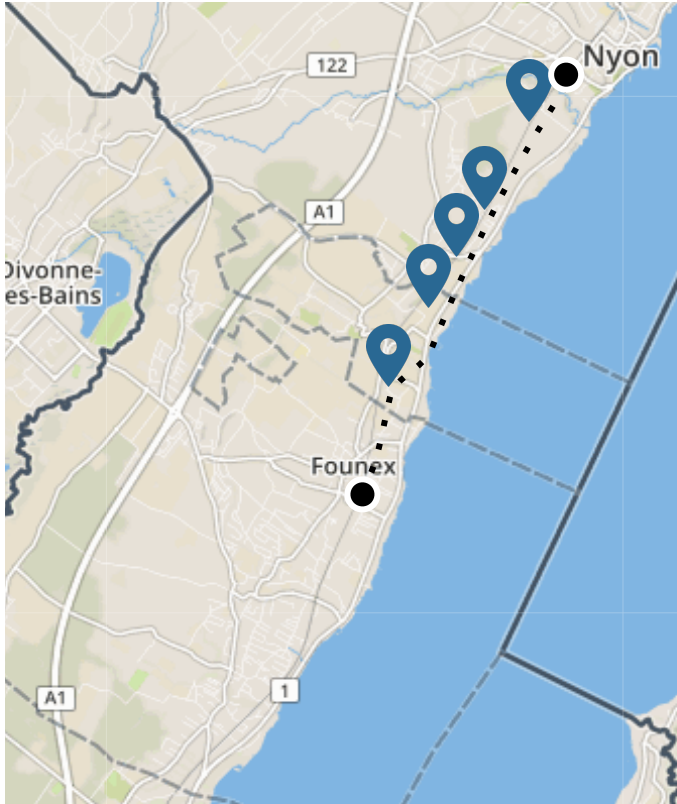
Accuracy of location data: vehicles



Why percentiles/medians? Outliers

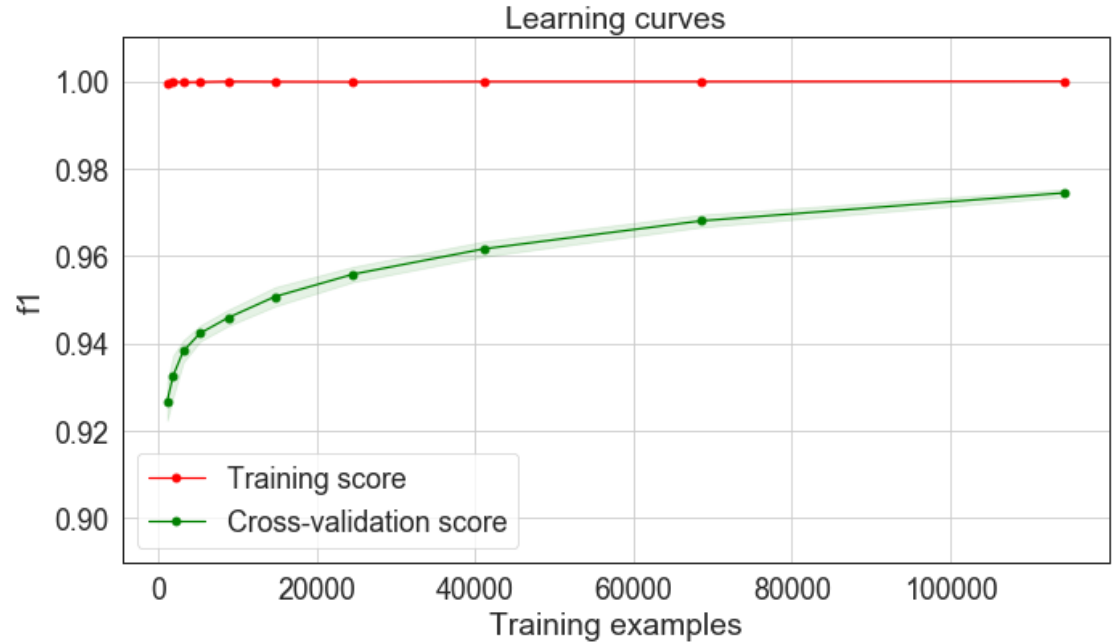


Features based on domain data

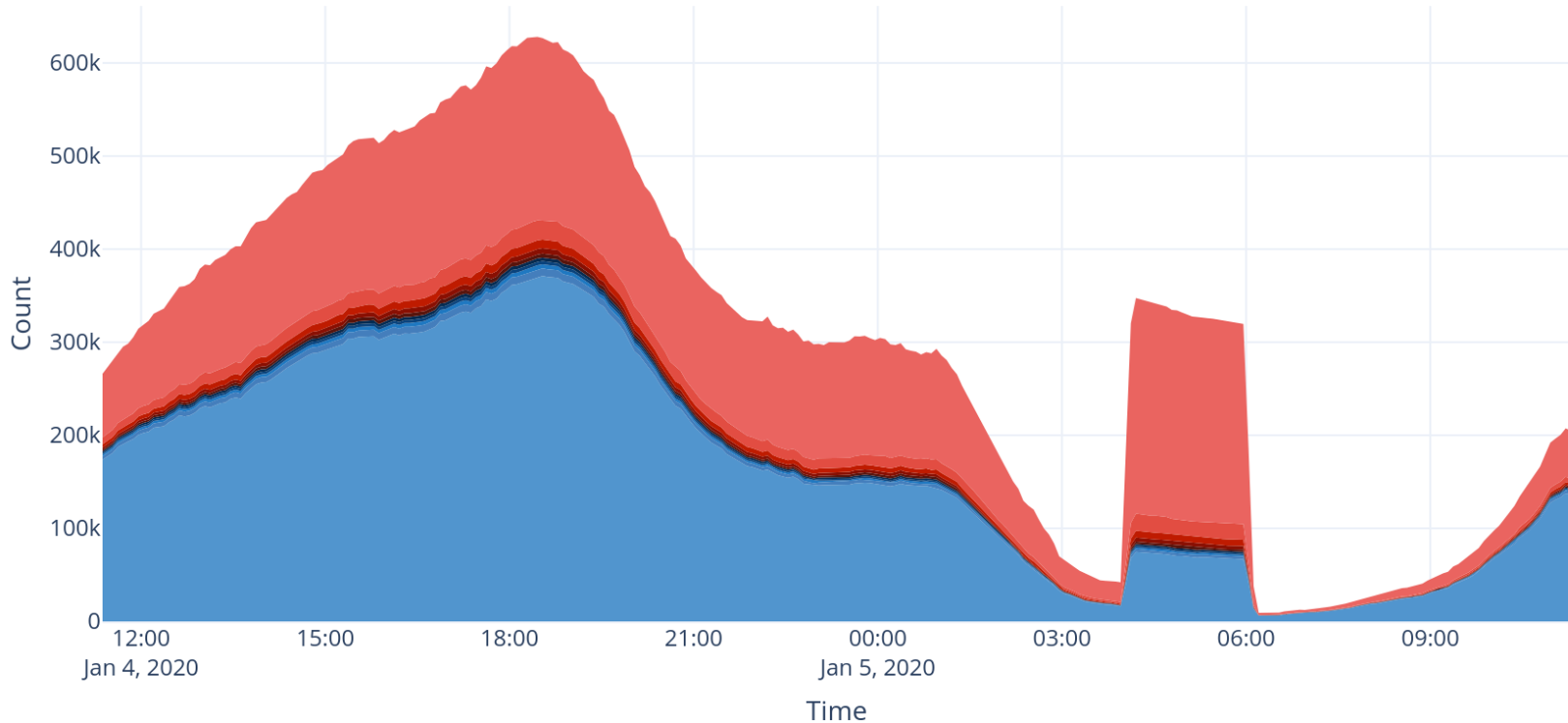


First model: random forest

- Quick to implement and to inspect
- Robust with a low # of training samples



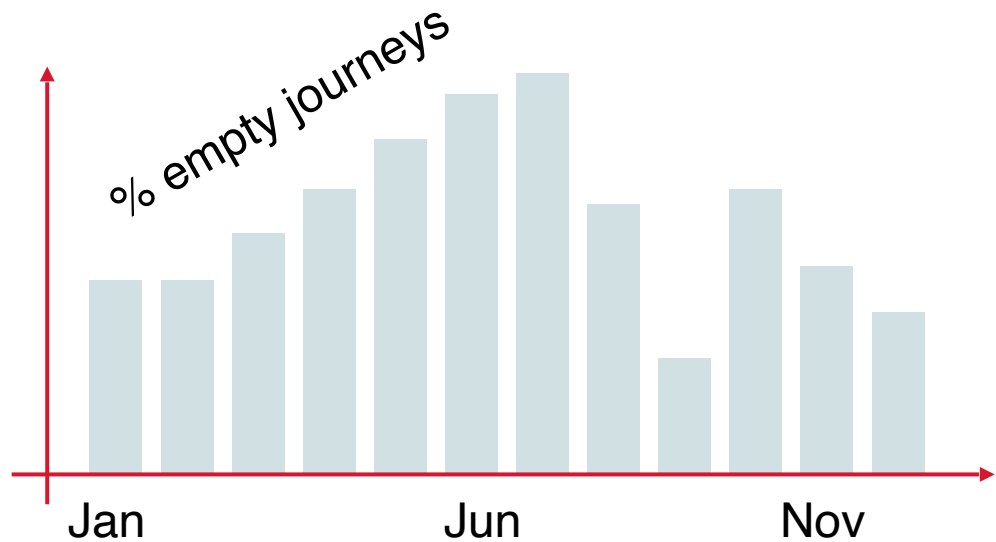
What happened with forgotten checkouts



Funiculars



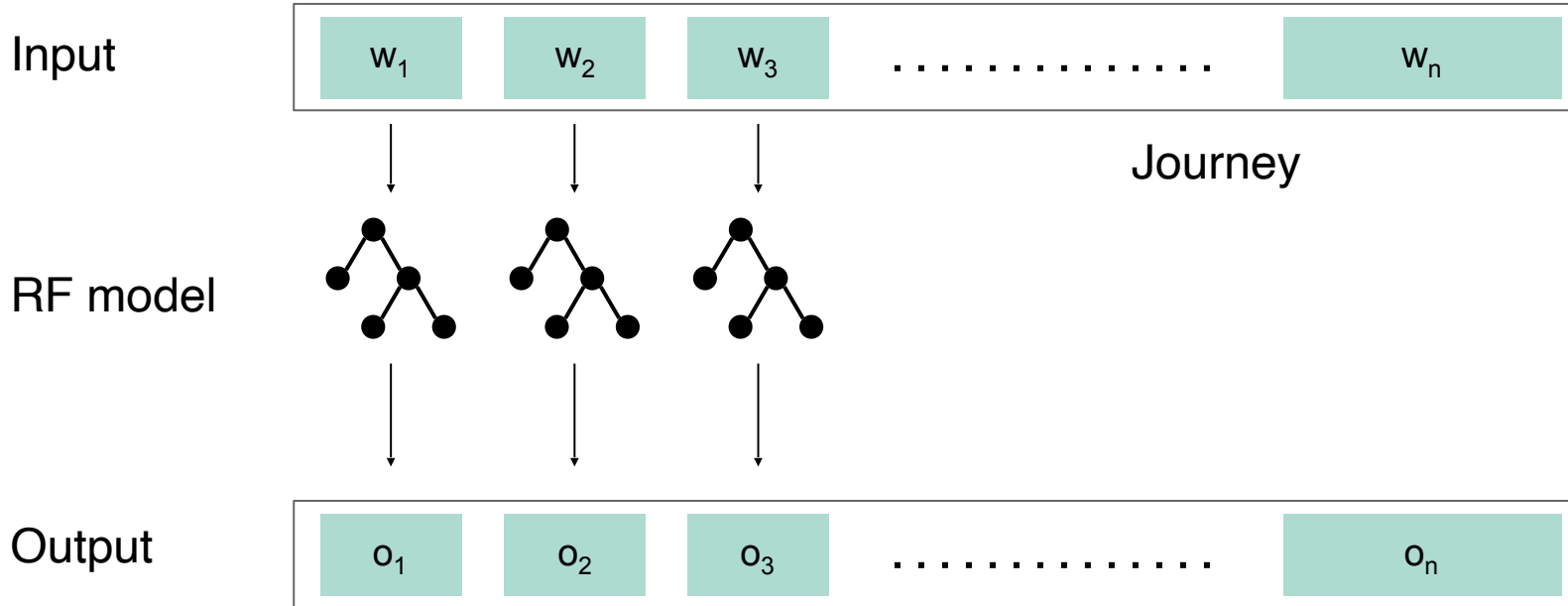
- Slow movement – can be confused with walks
- Feature that measures distance to the funi route



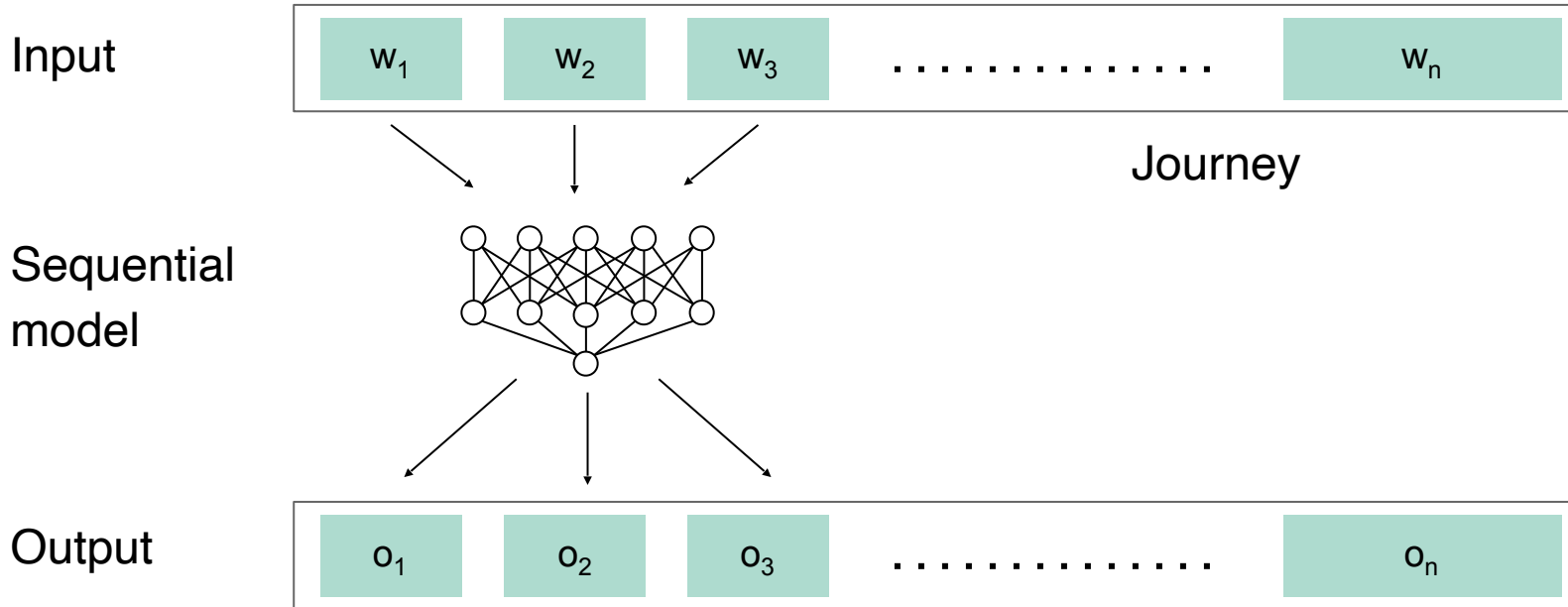
What's next?



The “problem” with Random Forest model



The advantages of NN models



Thank you for your attention

 [linkedin.com/in/rprokofyev](https://www.linkedin.com/in/rprokofyev)

